

General instructions

CAUTION

Read the operating instructions!

- The operating instructions provide an introduction to the safe use of the products.
- Read the operating instructions for all system components!
- Observe accident prevention regulations!
- Observe all local regulations!
- Confirm with a signature where appropriate.

NOTE

In the event of queries on installation, commissioning, operation or special conditions at the installation site, or on usage, please contact your sales partner or our customer service department on +49 2680 181-0.
 A list of authorised sales partners can be found at www.ewm-group.com.

Liability relating to the operation of this equipment is restricted solely to the function of the equipment. No other form of liability, regardless of type, shall be accepted. This exclusion of liability shall be deemed accepted by the user on commissioning the equipment.

The manufacturer is unable to monitor whether or not these instructions or the conditions and methods are observed during installation, operation, usage and maintenance of the equipment.

An incorrectly performed installation can result in material damage and injure persons as a result. For this reason, we do not accept any responsibility or liability for losses, damages or costs arising from incorrect installation, improper operation or incorrect usage and maintenance or any actions connected to this in any way.

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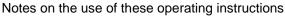
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2 Safety instructions

2.1 Notes on the use of these operating instructions

Working or operating procedures which must be closely observed to prevent imminent serious and even fatal injuries.

- Safety notes include the "DANGER" keyword in the heading with a general warning symbol.
- The hazard is also highlighted using a symbol on the edge of the page.

Working or operating procedures which must be closely observed to prevent serious and even fatal injuries.

- Safety notes include the "WARNING" keyword in the heading with a general warning symbol.
- The hazard is also highlighted using a symbol in the page margin.

Working or operating procedures which must be closely observed to prevent possible minor personal injury.

- The safety information includes the "CAUTION" keyword in its heading with a general warning symbol.
- The risk is explained using a symbol on the edge of the page.

CAUTION

Working and operating procedures which must be followed precisely to avoid damaging or destroying the product.

- The safety information includes the "CAUTION" keyword in its heading without a general warning symbol.
- The hazard is explained using a symbol at the edge of the page.

NOTE

Special technical points which users must observe.

Notes include the "NOTE" keyword in the heading without a general warning symbol.

Instructions and lists detailing step-by-step actions for given situations can be recognised via bullet points, e.g.:

· Insert the welding current lead socket into the relevant socket and lock.



2.2 Explanation of icons

Symbol	Description
PA	Press
K	Do not press
	Turn
	Switch
	Switch off machine
	Switch on machine
ENTER	ENTER (enter the menu)
NAVIGATION	NAVIGATION (Navigating in the menu)
EXIT	EXIT (Exit the menu)
4 s	Time display (example: wait 4s/press)
	Interruption in the menu display (other setting options possible)
X	Tool not required/do not use
Î	Tool required/use

General



2.3 General

A DANGER



Electromagnetic fields!

The power source may cause electrical or electromagnetic fields to be produced which could affect the correct functioning of electronic equipment such as IT or CNC devices, telecommunication lines, power cables, signal lines and pacemakers.

- Observe the maintenance instructions! (see Maintenance and Testing chapter)
- Unwind welding leads completely!
- Shield devices or equipment sensitive to radiation accordingly!
- The correct functioning of pacemakers may be affected (obtain advice from a doctor if necessary).



Do not carry out any unauthorised repairs or modifications!

To avoid injury and equipment damage, the unit must only be repaired or modified by specialist, skilled persons!

- The warranty becomes null and void in the event of unauthorised interference.
- Appoint only skilled persons for repair work (trained service personnel)!



Electric shock!

Welding machines use high voltages which can result in potentially fatal electric shocks and burns on contact. Even low voltages can cause you to get a shock and lead to accidents.

- Do not touch any live parts in or on the machine!
- · Connection cables and leads must be free of faults!
- Switching off alone is not sufficient!
- Place welding torch and stick electrode holder on an insulated surface!
- The unit should only be opened by specialist staff after the mains plug has been unplugged!
- Only wear dry protective clothing!
- Wait for 4 minutes until the capacitors have discharged!

▲ WARNING



Risk of injury due to radiation or heat!

Arc radiation results in injury to skin and eyes.

Contact with hot workpieces and sparks results in burns.

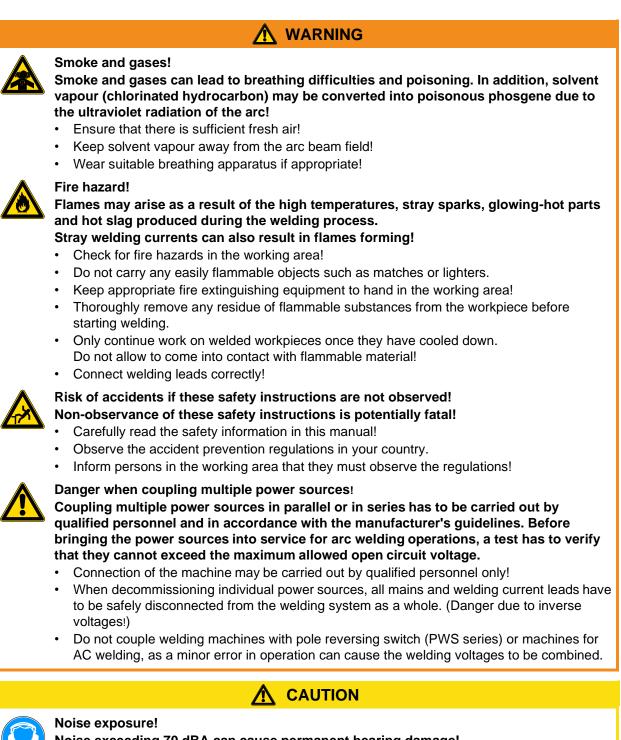
- Use welding shield or welding helmet with the appropriate safety level (depending on the application)!
- Wear dry protective clothing (e.g. welding shield, gloves, etc.) according to the relevant regulations in the country in question!
- Protect persons not involved in the work against arc beams and the risk of glare using safety curtains!

Explosion risk!

Apparently harmless substances in closed containers may generate excessive pressure when heated.

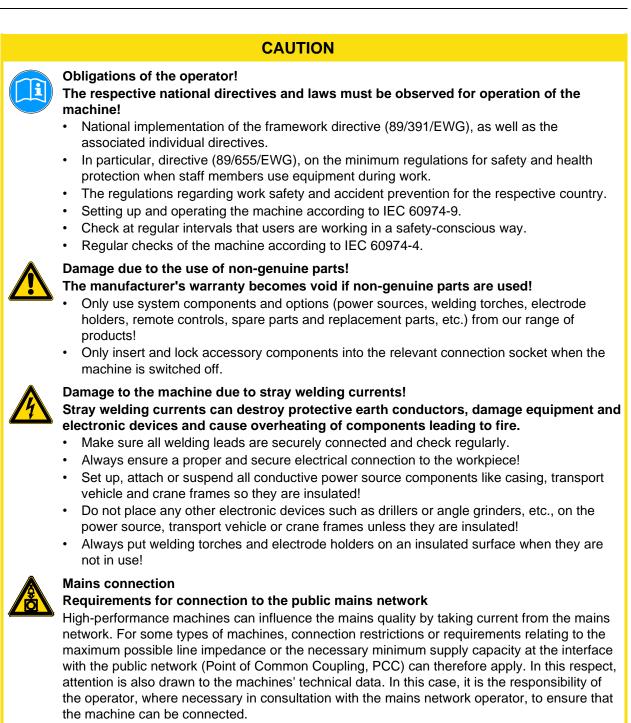
- Move containers with inflammable or explosive liquids away from the working area!
- · Never heat explosive liquids, dusts or gases by welding or cutting!

ewm



Noise exceeding 70 dBA can cause permanent hearing damage!

- Wear suitable ear protection!
- Persons located within the working area must wear suitable ear protection!





CAUTION



EMC Machine Classification

In accordance with IEC 60974-10, welding machines are grouped in two electromagnetic compatibility classes (see technical data):

Class A machines are not intended for use in residential areas where the power supply comes from the low-voltage public mains network. When ensuring the electromagnetic compatibility of class A machines, difficulties can arise in these areas due to interference not only in the supply lines but also in the form of radiated interference.

Class B machines fulfil the EMC requirements in industrial as well as residential areas, including residential areas connected to the low-voltage public mains network.

Setting up and operating

When operating arc welding systems, in some cases, electro-magnetic interference can occur although all of the welding machines comply with the emission limits specified in the standard. The user is responsible for any interference caused by welding.

In order to **evaluate** any possible problems with electromagnetic compatibility in the surrounding area, the user must consider the following: (see also EN 60974-10 Appendix A)

- Mains, control, signal and telecommunication lines
- Radios and televisions
- Computers and other control systems
- · Safety equipment
- The health of neighbouring persons, especially if they have a pacemaker or wear a hearing aid
- Calibration and measuring equipment
- · The immunity to interference of other equipment in the surrounding area
- The time of day at which the welding work must be carried out

Recommendations for reducing interference emission

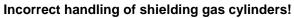
- · Mains connection, e.g. additional mains filter or shielding with a metal tube
- · Maintenance of the arc welding equipment
- · Welding leads should be as short as possible and run closely together along the ground
- · Potential equalization
- Earthing of the workpiece. In cases where it is not possible to earth the workpiece directly, it should be connected by means of suitable capacitors.
- Shielding from other equipment in the surrounding area or the entire welding system

Transport and installation



2.4 Transport and installation





Incorrect handling of shielding gas cylinders can result in serious and even fatal injury.

- Observe the instructions from the gas manufacturer and in any relevant regulations concerning the use of compressed air!
- Place shielding gas cylinders in the holders provided for them and secure with fixing devices.
- · Avoid heating the shielding gas cylinder!



Risk of accident due to improper transport of machines that may not be lifted! Do not lift or suspend the machine! The machine can fall down and cause injuries! The handles and brackets are suitable for transport by hand only!

• The machine may not be lifted by crane or suspended!



Risk of tipping!

There is a risk of the machine tipping over and injuring persons or being damaged itself during movement and set up. Tilt resistance is guaranteed up to an angle of 10° (according to EN 60974-A2).

- Set up and transport the machine on level, solid ground!
- Secure add-on parts using suitable equipment!
- Replace damaged wheels and their fixing elements!
- Fix external wire feed units during transport (avoid uncontrolled rotation)!



Damage due to supply lines not being disconnected!

During transport, supply lines which have not been disconnected (mains supply leads, control leads, etc.) may cause hazards such as connected equipment tipping over and injuring persons!

Disconnect supply lines!

CAUTION



Equipment damage when not operated in an upright position! The units are designed for operation in an upright position!

- Operation in non-permissible positions can cause equipment damage.
- Only transport and operate in an upright position!



2.4.1 Ambient conditions



Installation site!

The machine must not be operated in the open air and must only be set up and operated on a suitable, stable and level base!

- The operator must ensure that the ground is non-slip and level, and provide sufficient lighting for the place of work.
- Safe operation of the machine must be guaranteed at all times.

CAUTION



Equipment damage due to dirt accumulation!

Unusually high quantities of dust, acid, corrosive gases or substances may damage the equipment.

- Avoid high volumes of smoke, vapour, oil vapour and grinding dust!
- Avoid ambient air containing salt (sea air)!



Non-permissible ambient conditions!

Insufficient ventilation results in a reduction in performance and equipment damage.

- Observe the ambient conditions!
- Keep the cooling air inlet and outlet clear!
- Observe the minimum distance of 0.5 m from obstacles!

2.4.1.1 In operation

Temperature range of the ambient air:

-10 °C to +40 °C*

Relative air humidity:

- Up to 50% at 40 °C
- Up to 90% at 20 °C

NOTE

* Ambient temperature depends on coolant! Observe the coolant temperature range for the welding torch cooling!

2.4.1.2 Transport and storage

Storage in an enclosed space, temperature range of the ambient air:

-30 °C to +70 °C

Relative air humidity

Up to 90% at 20 °C

Applications



3 Intended use

🔥 WARNING



Hazards due to improper usage!

Hazards may arise for persons, animals and material objects if the equipment is not used correctly. No liability is accepted for any damages arising from improper usage!

- The equipment must only be used in line with proper usage and by trained or expert staff!
- Do not modify or convert the equipment improperly!

3.1 Applications

3.2 Plasma welding

In plasma welding a plasma jet is used as heat source. Plasma is an electrically conducting gas that has been heated to a very high temperature by an arc. In the plasma torch the flowing plasma gas (argon) is ionised by high-frequency pulses and the pilot arc ignites. The pilot arc then burns between the negative tungsten electrode and the nozzle (anode), thus ionising the gas column between nozzle and positive workpiece. In this way a non-contact ignition of the arc is possible.

3.3 TIG welding

TIG welding with alternating or direct current. Arc ignition optionally by means of non-contact HF ignition or contact ignition with Liftarc.

3.3.1 TIG activArc welding

The EWM activArc process, thanks to the highly dynamic controller system, ensures that the power supplied is kept virtually constant in the event of changes in the distance between the welding torch and the weld pool, e.g. during manual welding. Voltage losses as a result of a shortening of the distance between the torch and molten pool are compensated by a current rise (ampere per volt - A/V), and vice versa. This helps prevents the tungsten electrode sticking in the molten pool and the tungsten inclusions are reduced. This is particularly useful in tacking and in spot welding.

3.3.2 spotArc

This process is suitable for tack welding or joint welding of metal sheets made from steel and CrNi alloys up to a thickness of approximately 2.5 mm. Metal sheets of different thicknesses can also be welded on top of one another. As this is a one-sided process, it is also possible to weld metal sheets onto tubular sections such as round or square pipes. In arc spot welding, the arc melts through the upper metal sheet and the lower metal sheet is melted onto it. This produces flat, fine-textured welding tacks which require little or no post weld work, even in visible areas.

3.3.3 TIG hot wire welding

The TIG hot wire welding system technology is based on the TIG cold wire welding system technology. A wire feed system transports the wire-like welding consumable, which is heated at the stick-out between contact tip and weld pool contact point by means of resistance heating. A second power source is required for this resistance heating. Its secondary power circuit is closed by the wire's permanent contact with the weld pool. The process of pre-heating the wire can be controlled in a wide range by the selected hot wire power.

By pre-heating the wire, the energy taken from the weld pool for melting the wire can be reduced. This allows a significantly larger amount of welding consumables to be used at a higher welding speed, thus reducing the energy per unit length.

3.3.4 TIG cold wire welding

Cold wire welding is a variant of TIG welding featuring mechanically fed filler material. With this process, cold welding wire is melted, without power, in the arc of a tungsten electrode.



3.4 Use and operation solely with the following machines

- BUSINT X11
- RINT X12
- T drive 4 Rob 3 RE
- T drive 4 Rob 3 LI
- cool82 U44
- cool82 U45
- RK 1
- RK 2
- RK 3

3.5 Documents which also apply

3.5.1 Warranty

NOTE

For further information, please see the accompanying supplementary sheets "Machine and Company Data, Maintenance and Testing, Warranty"!

3.5.2 Declaration of Conformity

The designated machine conforms to EC Directives and standards in terms of its design and construction:

- EC Low Voltage Directive (2006/95/EC),
- EC EMC Directive (2004/108/EC),

This declaration shall become null and void in the event of unauthorised modifications, improperly conducted repairs, non-observance of the deadlines for the repetition test and / or non-permitted conversion work not specifically authorised by the manufacturer.

The original copy of the declaration of conformity is enclosed with the unit.

3.5.3 Welding in environments with increased electrical hazards



In environments with increased electrical nazards In compliance with IEC / DIN EN 60974, VDE 0544 the machines can be used in environments with an increased electrical hazard.

3.5.4 Service documents (spare parts and circuit diagrams)

DANGER

Do not carry out any unauthorised repairs or modifications! To avoid injury and equipment damage, the unit must only be repaired or modified by specialist, skilled persons!

- The warranty becomes null and void in the event of unauthorised interference.
- Appoint only skilled persons for repair work (trained service personnel)!

Original copies of the circuit diagrams are enclosed with the unit.

Spare parts can be obtained from the relevant authorised dealer.

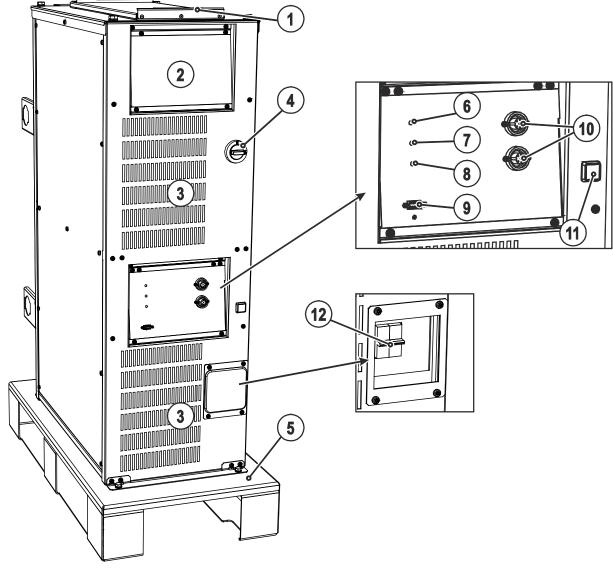
3.5.5 Calibration/Validation

We hereby confirm that this machine has been tested using calibrated measuring equipment, as stipulated in IEC/EN 60974, ISO/EN 17662, EN 50504, and complies with the admissible tolerances. Recommended calibration interval: 12 months



4 Machine description – quick overview

4.1 Front view







tem	Symbol	Description
1		Carrier plate for system components
		only hot wire version
2		Machine control
		See Machine control – operating elements chapter
3		Cooling air inlet
4		Main switch, machine on/off
5		ROB XX2 pallet
	#	Transport pallet
6		Operating state signal lamp
	W	Lights up when the machine is ready for use.
7	Ĩ	Operating problem signal light
		(see chapter "Rectifying faults")
8	F	Welding process signal lamp
	<u> </u>	Lights up when the welding process runs.
9		PC interface, serial (D-Sub connection socket, 9-pole)
10		7-pole connection socket (digital)
		For connecting digital accessory components
11	'nÒ	Pilot arc button with signal light
	L ₹Q	Signal light off: pilot arc off
	-	Signal light on: pilot arc lit
12		Automatic cutouts
		Fuse protection for the pilot arc power source
		 Fuse protection for the reverse cooling unit's protective contact socket (back of machine)

Machine description – quick overview



Rear view

4.2 Rear view

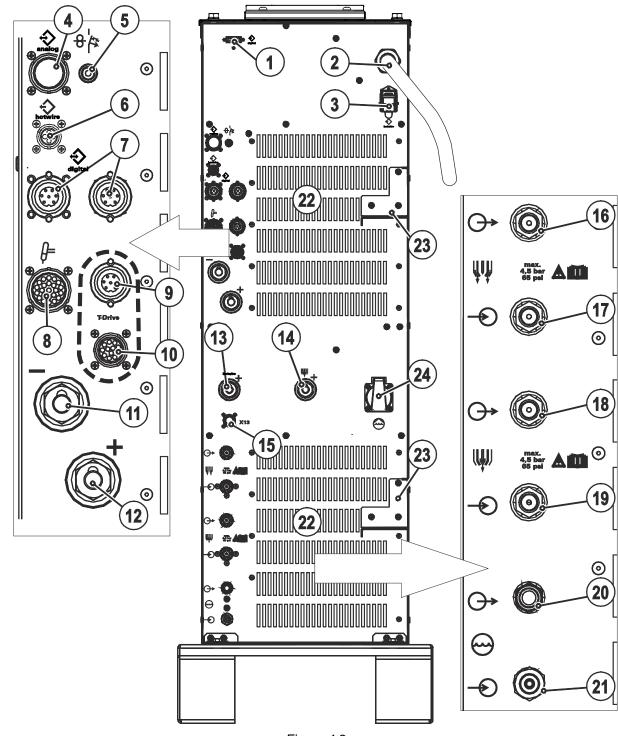


Figure 4-2



ltem	Symbol	Description
1	digital	Interfaces connection socket (15-pole)
2		Mains connection cable
3		Mains connection, hot wire power source
		Power supply for hot wire power source
4	analog	19-pole mechanised welding interface (analogue) (See chapter entitled "Design and function > interfaces".)
5	17-	Key button, automatic cutout Wire feed motor supply voltage fuse
	I	press to reset a triggered fuse
6	hotWire	Control lead connection, hot wire power source 4-pole connection to the hot wire power source
7	\Rightarrow	7-pole connection socket (digital) For connecting digital accessory components
8		23-pole connection socket (analogue) Mechanised welding torch connection
9	8	7-pole connection socket (digital) Wire feed unit connection
10	8	12-pole connection socket (analogue) Wire feed unit connection
11		Connection socket, welding current - Welding torch connection
12		Connection socket, "+" welding current Connection for workpiece lead
13	╉	Connection socket for "+" welding current Connection to TIG power source for hot wire application
14	╋	Pilot current connection socket Plasma welding torch nozzle potential
15	X13	"Insufficient wire" sensor connection
16	ŴŴ	G1/4" connecting nipple, shielding gas, outlet Connection to welding torch
17	-Ð₩	Connecting nipple G1/4" shielding gas, inlet Connection to pressure regulator
18		G1/4" connecting nipple, plasma gas, outlet Connection to welding torch
19	-€ ₩	Connecting nipple G1/4" plasma gas, inlet Connection to pressure regulator
20	Θ	Quick connect coupling (red) Coolant return to cooling unit
21	-	Rapid-action closure nipple Coolant return from welding torch
22		Cooling air outlet
23		Intermediate hose package strain relief
24	Θ	Cooling unit voltage supply Protective contact socket

Machine control (Mode RC - on)



4.3 Machine control (Mode RC - on)

NOTE This welding machine is operated in the "RC – on, remote-controlled" mode as a factory T ST setting. RC - on: The machine is operated via an external interface in this mode. The majority of the machine control's operating elements will be deactivated and are only used to monitor the welding data. RC - off: The welding machine is operated via the machine control. Refer to the "Machine configuration menu" chapter to switch between the operating modes. т з.22 3) 1,0 Sec (Puls 1,6 Automatic 2.0 SOC kHz Netsyn. 58C 201 AMP% 2,4 Master AC 0 AMP% (4)Slave S 3.2 AC/DC **___** Hz kHz . % activArc sec sec AMP HOLD sec **DC** –(5 VOLT Hz / kHz % $AC \sim$ JOB [7] Synergic PROG DC CrNi Fe/St spotArc 6 DC Cu CuZn **BB** AC AIMg 8 AISi AC C A199 Manuell <u>∧</u> <u>m</u> s ce

Figure 4-3

Item	Symbol	Description	
1		Tungsten electrode diameter / Ignition optimisation / Spherical cap formation button \emptyset 1.0mm, \emptyset 1.6mm, \emptyset 2.0mm, \emptyset 2.4mm, \emptyset 3.2mm, \emptyset 4.0mm or greater Best ignition and stabilisation of the arc (DC, AC) and optimum spherical cup formation in the tungsten electrode according to the electrode diameter being used. The adjustable welding current is limited to the maximum permissible welding current of the tungsten electrode.	
2	()	Gas test/rinse hose package button see "Shielding gas setting" chapter	
3	 Fror/status indicators Collective interference signal light Collective interference signal light Water deficiency signal light (welding torch cooling) F Excess temperature signal light S afety sign signal light 		



ltem	Symbol	Description
4	Function sequence (see next chapter)	
5		Status displays
		HOLD After each completed welding task, the last values used in the welding process for the welding current and welding voltage are shown on the displays, and the signal light will be on
		DC — Direct current welding
		AC Alternating current welding
		DC — and AC \sim simultaneously: Alternating current welding, AC special
6		Welding parameter setting rotary transducer
		Setting of all parameters such as welding current, sheet metal thickness, gas pre-flow time, etc.
7		Three-figure LED display
		Welding parameter display (see also chap. "Welding data display").
8		Display switching button
		 Material thickness display VOLT Welding voltage display JOB JOB number display PROG Program number display

Machine description – quick overview Machine control (Mode RC - on)



4.3.1 **Function sequence**

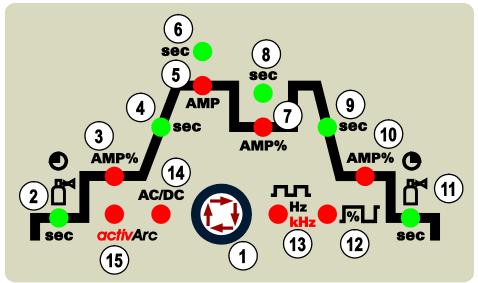


Figure 4-4

ltem	Symbol	Description	Description			
1		Select welding parameters button This button is used to select the welding parameters depending on the welding process and operating mode used.				
2	sec	Gas pre-flow time (TIG)				
		absolute setting range 0.0 sec to 20.0 sec (0				
3	AMP%	Ignition current (TIG)	Hotstart current (MMA)			
		Percentage of the main current. Setting range 1 % to 200 %	Percentage of the main current. Setting range 1 % to 200 %			
		(1 % increments). There are no pulses	(1 % increments).			
		during the ignition current phase.				
4	sec	Up-slope time (TIG)	Hotstart time (MMA)			
		Setting ranges: 0.00 s to 20.0 s	Setting ranges: 0.00 s to 20.0 s			
		(0.1 s increments).	(0.1 s increments).			
		The up-slope time can be set separately for non-latched and latched.				
5	AMP	Main current (TIG) / pulse current	Main current (MMA)			
5		I min to I max (1 A increments)	I min to I max (1 A increments)			
6	sec	Pulse time / slope time from AMP% to AM				
•		 Pulse time setting range: 0.01 s to 20.0 s 				
		(0.01 s increments < 0.5 s; 0.1 s increme				
		Slope time (tS2) setting range: 0.0 s to 2	0.0 s			
		(see chapter "Pulse variants")	TIC AC Special			
		TIG pulses The pulse time applies to the main current	TIG AC Special The pulse time applies to the AC phase for			
		phase (AMP) for pulses.	AC special.			
7	AMP%	Secondary current (TIG) / pulse pause cu	irrent			
		Setting range 1 % to 100 % (1 % increments	s). Percentage of the main current.			
8	sec	Pulse break time/slope time from AMP to				
		Pulse break setting range: 0.01 sec to 20				
		(0.01 sec increments < 0.5 sec; 0.1 sec i	•			
		 Slope time (tS1) setting range: 0.0 sec to (see chapter "Pulse variants"). 	0 20.0 Sec			
		TIG pulses: The pulse break time applies to	the secondary current phase (AMP%)			
		TIG AC Special: The pulse break time applie	,			



ltem	Symbol	Description
9	sec	Down-slope time (TIG)
		0.00 s to 20.0 s (0.1 s increments).
		The down-slope time can be set separately for non-latched and latched.
10	AMP%	End-crater current (TIG)
		Setting range 1 % to 200 % (1 % increments). Percentage of the main current.
11	sec	Gas post-flow time (TIG)
		Setting ranges: 0.00 sec to 40.0 sec (0.1 sec increments).
12	%	Alternating current balance (TIG AC)
		Max. setting range: -30 % to +30 % (1 % increments). The setting range may also be
		lower depending on the factory setting.
		Optimisation of cleaning effect and fusion penetration characteristics.
		Balance fast TIG DC pulses
		Setting range: 1 % to +99 % (1 % increments)
13	лл #2	Alternating current frequency (TIG AC)
	kHz	50 Hz to 200 Hz (1 Hz increments).
		Constriction and stabilisation of the arc:
		The cleaning effect increases with a greater frequency. Particularly thin panels (welding
		with a low current), anodised sheet aluminium or highly contaminated articles for
		welding can be welded and cleaned perfectly at a higher frequency.
		Frequency fast TIG DC pulses
		Setting range: 50 Hz to 15 kHz
14	AC/DC	Welding current polarity, MMA
		(see chap. "Switching the welding current polarity")
15	activArc	activArc TIG welding process
		Switch activArc on or off
		Correct the activArc characteristic (setting range: 0 to 100)

Machine description – quick overview

Machine control (Mode RC - off)



4.4 Machine control (Mode RC - off)

As the plasma welding process is based directly on the TIG welding process, the TIG descriptions are used for plasma welding, with just a few differences.

NOTE

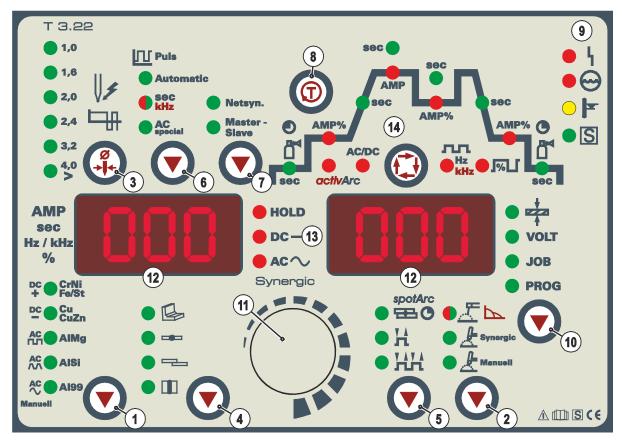


Figure 4-5

ltem	Symbol	Description		
1	\bigcirc	Polarity changeover (TIG manual) butto	on	Select material type (TIG Synergic) key button
		DC welding with positive polarity on the electrode holder in relation to the workpiece (pole reversing switch, MMA only).	DC + 🛑 CrNi Fe/St	Chrome/nickel alloys / iron / steel alloys
		DC welding with negative polarity at the torch (or electrode holder) with respect to the workpiece.	DC — Cu CuZn	Copper / copper alloys (bronzes) / copper/zinc alloys (brass)
		AC welding with rectangular current output wave form. Maximum power loading and safe welding.		Aluminium/magnesium alloys
		AC welding with trapezoidal current output wave form. An all-rounder, suitable for most applications.		Aluminium/silicon alloys
		AC welding with sinusoidal current output wave form. Low noise level.	AC^ AI99	99% aluminium
2	\bigcirc	"Welding process" button Image: Synergic synergic synergic process Image: Synergic synergic synergic process Image: Synergic synerg	parameter setti	ing)



Item	Symbol	Description
3		Tungsten electrode diameter / Ignition optimisation / Spherical cap formation button \emptyset 1.0mm, \emptyset 1.6mm, \emptyset 2.0mm, \emptyset 2.4mm, \emptyset 3.2mm, \emptyset 4.0mm or greater Best ignition and stabilisation of the arc (DC, AC) and optimum spherical cup formation in the tungsten electrode according to the electrode diameter being used. The adjustable welding current is limited to the maximum permissible welding current of the
		tungsten electrode.
4		Select seam type button Fillet weld Butt joint Fillet weld - lap joint Vertical-down
5		Operating mode button
5		spotArc SpotArc SpotArc Non-latched Latched
6		TIG pulse welding
		Automatic TIG automated pulses (frequency and balance) Sec TIG pulses with times, green light / Fast TIG DC pulses with frequency and balance, red light AC special
7		Synchronisation types key button (two-sided, simultaneous welding)
•		 Synchronisation via mains voltage Synchronisation via cable
8	(()	Gas test/rinse hose package button see "Shielding gas setting" chapter
9	• ५	Error/status indicators
	• • •	Collective interference signal light
	Ť.	• Water deficiency signal light (welding torch cooling)
	• <u></u>	Excess temperature signal light
10		Display switching button
10		Material thickness display VOLT Welding voltage display JOB JOB number display PROG Program number display
11		Welding parameter setting rotary transducer Setting of all parameters such as welding current, sheet metal thickness, gas pre-flow time, etc.
12	000	Three-figure LED display Welding parameter display (see also chap. "Welding data display").
13		 Status displays HOLD After each completed welding task, the last values used in the welding process for the welding current and welding voltage are shown on the displays, and the signal light will be on DC Direct current welding
		AC \sim Alternating current welding DC — and AC \sim simultaneously: Alternating current welding, AC special

Machine description – quick overview Machine control (Mode RC - off)



ltem	Symbol	Description
14		Function sequence (see next chapter)



4.4.1 Function sequence

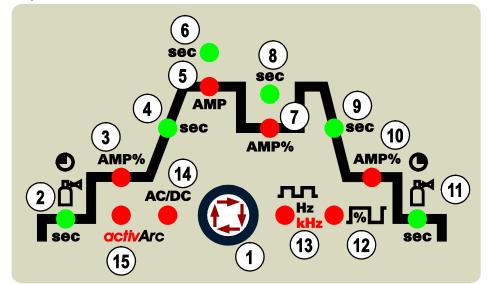


Figure 4-6

ltem	Symbol	Description		
1		Select welding parameters button		
			rameters depending on the welding process	
		and operating mode used.		
2	sec	,	Gas pre-flow time (TIG)	
		absolute setting range 0.0 sec to 20.0 sec (
3	AMP%	Ignition current (TIG)	Hotstart current (MMA)	
		Percentage of the main current.	Percentage of the main current. Setting	
		Setting range 1 % to 200 % (1 % increments). There are no pulses	range 1 % to 200 % (1 % increments).	
		during the ignition current phase.		
4	sec	Up-slope time (TIG)	Hotstart time (MMA)	
		Setting ranges: 0.00 s to 20.0 s	Setting ranges: 0.00 s to 20.0 s	
		(0.1 s increments).	(0.1 s increments).	
		The up-slope time can be set separately		
		for non-latched and latched.		
5	AMP	Main current (TIG) / pulse current	Main current (MMA)	
		I min to I max (1 A increments)	I min to I max (1 A increments)	
6	sec	Pulse time / slope time from AMP% to AMP		
		Pulse time setting range: 0.01 s to 20.0 s		
		(0.01 s increments < 0.5 s; 0.1 s increments > 0.5 s)		
		 Slope time (tS2) setting range: 0.0 s to 2 (see chapter "Pulse variants") 	0.0 \$	
		TIG pulses	TIG AC Special	
		The pulse time applies to the main current	The pulse time applies to the AC phase for	
		phase (AMP) for pulses.	AC special.	
7	AMP%	Secondary current (TIG) / pulse pause current		
		Setting range 1 % to 100 % (1 % increment	s). Percentage of the main current.	
8	sec	Pulse break time/slope time from AMP to AMP%		
		Pulse break setting range: 0.01 sec to 20		
		(0.01 sec increments < 0.5 sec; 0.1 sec i	,	
		Slope time (tS1) setting range: 0.0 sec to (ass shorter "Pulse variante")	o 20.0 sec	
		(see chapter "Pulse variants").		
		TIG pulses: The pulse break time applies to		
	1	TIG AC Special: The pulse break time appli	es to the DC phase with AC special.	

Machine description – quick overview Machine control (Mode RC - off)



ltem	Symbol	Description	
9	sec	Down-slope time (TIG)	
-		0.00 s to 20.0 s (0.1 s increments).	
		The down-slope time can be set separately for non-latched and latched.	
10	AMP% End-crater current (TIG)		
		Setting range 1 % to 200 % (1 % increments). Percentage of the main current.	
11	sec	Gas post-flow time (TIG)	
		Setting ranges: 0.00 sec to 40.0 sec (0.1 sec increments).	
12	1%	Alternating current balance (TIG AC)	
		Max. setting range: -30 % to +30 % (1 % increments). The setting range may also be	
		lower depending on the factory setting.	
		Optimisation of cleaning effect and fusion penetration characteristics.	
		Balance fast TIG DC pulses	
		Setting range: 1 % to +99 % (1 % increments)	
13		Alternating current frequency (TIG AC)	
	kHz	50 Hz to 200 Hz (1 Hz increments).	
		Constriction and stabilisation of the arc:	
		The cleaning effect increases with a greater frequency. Particularly thin panels (welding	
		with a low current), anodised sheet aluminium or highly contaminated articles for	
		welding can be welded and cleaned perfectly at a higher frequency.	
		Frequency fast TIG DC pulses	
		Setting range: 50 Hz to 15 kHz	
14	AC/DC	Welding current polarity, MMA	
		(see chap. "Switching the welding current polarity")	
15 activArc TIG welding process		activArc TIG welding process	
		Switch activArc on or off	
		Correct the activArc characteristic (setting range: 0 to 100)	



Plasmadrive

4.5 Plasmadrive

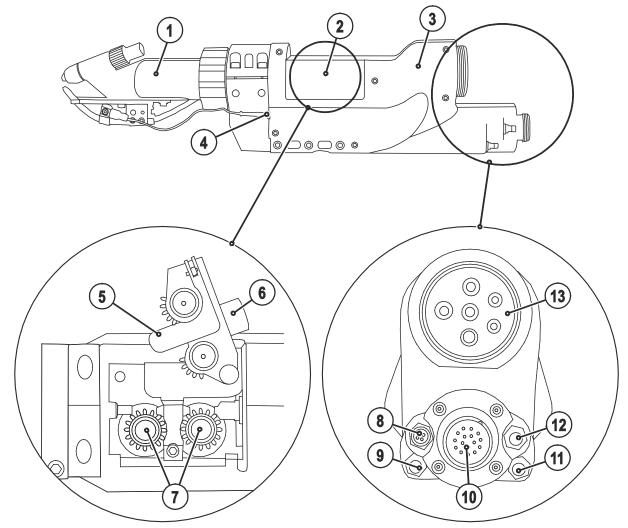


Figure 4-7

ltem	Symbol	Description
1		Welding torch head
2		Protective cap
		Cover for the wire feed mechanism and other operating elements.
		Depending on the machine series, additional stickers with information on the
		replacement parts and JOB lists will be located on the inside.
3		Plasmadrive
		Filler wire drive
4		Sensor voltage connection for the filler wire fusing detection
5		Contact pressure roller lock
6		Contact pressure setting (hexagon socket)
7		Drive roller
8		Anticollision device connection
9		Reverse inching button
10		Connection socket control lead welding torch
11		Wire inching key button
12		Gas test button
		Shielding gas flows for 20 s, or press again to stop the gas flow.
13		Torch hose package connection

"Insufficient wire" sensor 4.6

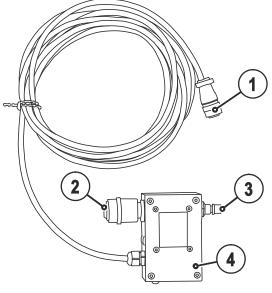


Figure 4-8

ltem	Symbol	Description
1		"Insufficient wire" sensor control lead plug
2		Wire feed rapid-action closure
		Connection to wire source
3		Wire exit rapid-action closure
		Connection to wire feed connection hose
4		"Insufficient wire" sensor
		A warning is issued as soon as the end of the wire (insufficient wire) is reached. The process will not be shut down.





5 Design and function

5.1 General



Risk of injury from electric shock!

- Contact with live parts, e.g. welding current sockets, is potentially fatal!
- Follow safety instructions on the opening pages of the operating instructions.
- Commissioning may only be carried out by persons who have the relevant expertise of working with arc welding machines!
- Connection and welding leads (e.g. electrode holder, welding torch, workpiece lead, interfaces) may only be connected when the machine is switched off!



Insulate the arc welder from welding voltage!

Not all active parts of the welding current circuit can be shielded from direct contact. To avoid any associated risks it is vital for the welder to adhere to the relevant safety regulations. Even low voltages can cause a shock and lead to accidents.

- Wear dry and undamaged protective clothing (shoes with rubber soles/welder's gloves made from leather without any studs or braces)!
 - Avoid direct contact with non-insulated connection sockets or connectors!
- Always place torches and electrode holders on an insulated surface!



Risk of burns on the welding current connection!

If the welding current connections are not locked, connections and leads heat up and can cause burns, if touched!

Check the welding current connections every day and lock by turning in clockwise direction, if necessary.



Risk of injury due to moving parts!

The wire feeders are equipped with moving parts, which can trap hands, hair, clothing or tools and thus injure persons!

- Do not reach into rotating or moving parts or drive components!
- Keep casing covers or protective caps closed during operation!



Risk of injury due to welding wire escaping in an unpredictable manner! Welding wire can be conveyed at very high speeds and, if conveyed incorrectly, may escape in an uncontrolled manner and injure persons!

- Before mains connection, set up the complete wire guide system from the wire spool to the welding torch!
- Remove the pressure rollers from the wire feeder if no welding torch is fitted!
- Check wire guide at regular intervals!
- Keep all casing covers or protective caps closed during operation!



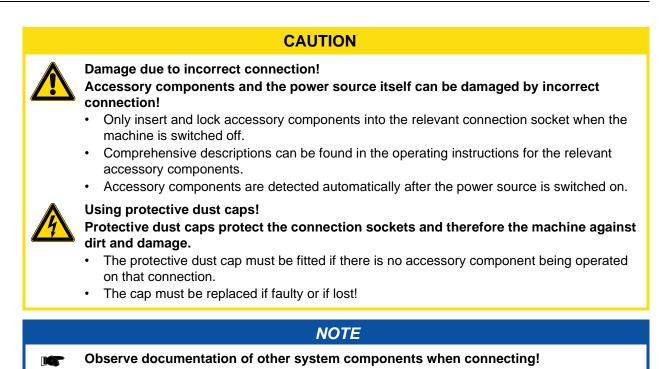
Risk from electrical current!

If welding is carried out alternately using different methods and if a welding torch and an electrode holder remain connected to the machine, the open-circuit/welding voltage is applied simultaneously on all cables.

• The torch and the electrode holder should therefore always be placed on an insulated surface before starting work and during breaks.

General









5.2 System integration

5.2.1 Plasma application with hot wire

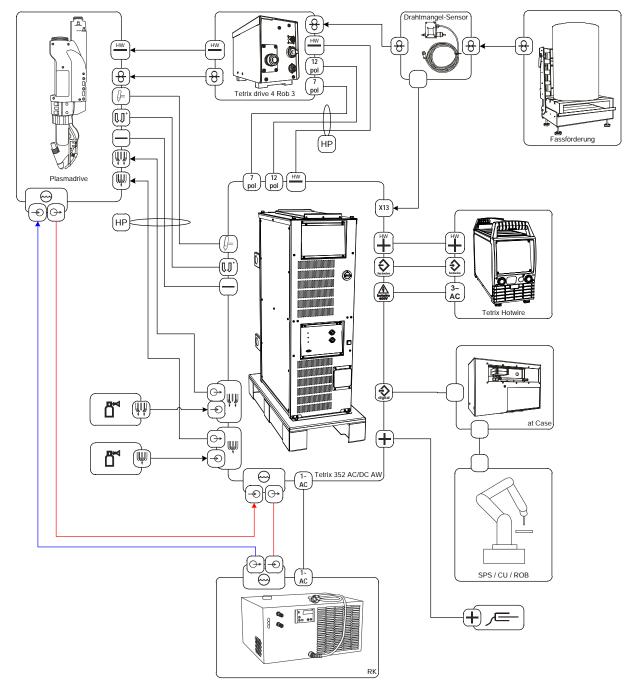


Figure 5-1

Design and function System integration



5.2.1.1 Legend

8	Wire feed (cold wire)
	Welding torch control lead (19-pole) connection socket
	Pilot arc current
\bigcirc	Welding current (minus potential)
	Shielding gas
	Plasma gas
\bigcirc	Welding torch coolant
	Input
$\bigcirc \rightarrow$	Output
(1~ AC	Reverse cooling unit supply voltage (230 V/AC, one-phase)
+	Welding current (plus potential, workpiece)
(12 pol	Wire feed unit control lead (12-pole) connection socket
(7 pol	Wire feed unit control lead (7-pole) connection socket
X13	"Insufficient wire" sensor control lead connection socket
digital	Interface connection socket (15-pole)
HP	Hose package (HP = hose package)
HW	Welding current (plus potential, hotwire) connection socket
HW	Welding current (minus potential, hotwire) connection socket
hotwire	Control lead, hot wire (signal output, 4-pole) connection socket
Antorite Hotoste	Supply voltage, hot wire power source connection socket



Transport and installation

5.3 Transport and installation



Risk of accident due to improper transport of machines that may not be lifted! Do not lift or suspend the machine! The machine can fall down and cause injuries! The handles and brackets are suitable for transport by hand only!

• The machine may not be lifted by crane or suspended!

\Lambda WARNING



Hazards due to improper mounting!

- In this system, the hot wire power source is positioned on the carrier platform of the mobile power source (filler wire).
- The machine may only be mounted and operated on the carrier platform for the hot wire power source!
- Safe operation of the machine must be guaranteed at all times!



5.3.1 Power source for hot wire welding

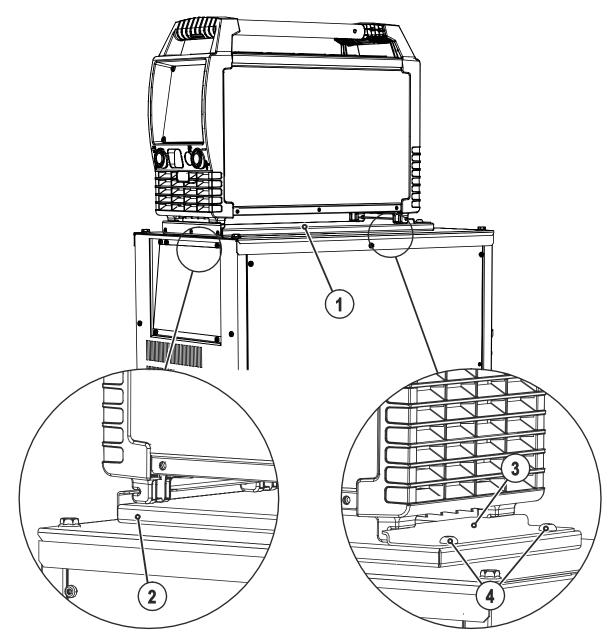


Figure 5-2

Item	Symbol	Description
1		Carrier platform for hot wire power source
2		Front holder
		Push the hot wire power source with the machine feet into the holder
3		Rear holder
		To fix, push the holder into the machine feet and
		secure with fixing screws.
4		Fixing screws (x 4)

5.4 Machine cooling

To obtain an optimal duty cycle from the power components, the following precautions should be observed:

- Ensure that the working area is adequately ventilated.
- Do not obstruct the air inlets and outlets of the machine.
- Do not allow metal parts, dust or other objects to get into the machine.



5.5 Workpiece lead, general



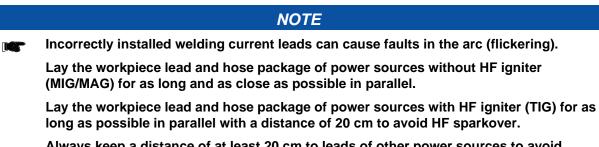
Risk of burns due to incorrect connection of the workpiece lead! Paint, rust and dirt on the connection restrict the power flow and may lead to stray welding currents.

Stray welding currents may cause fires and injuries!

- Clean the connections!
- Fix the workpiece lead securely!
- Do not use structural parts of the workpiece as a return lead for the welding current!
- Take care to ensure faultless power connections!



5.6 Notes on the installation of welding current leads



Always keep a distance of at least 20 cm to leads of other power sources to avoid interferences.

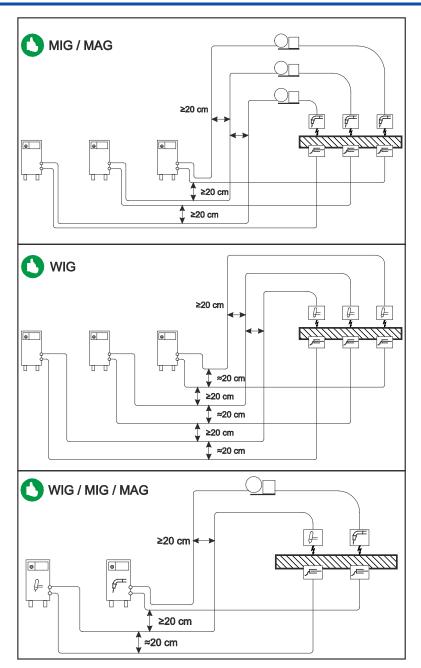


Figure 5-3



Design and function

Notes on the installation of welding current leads



Use an individual welding lead to the workpiece for each welding machine!

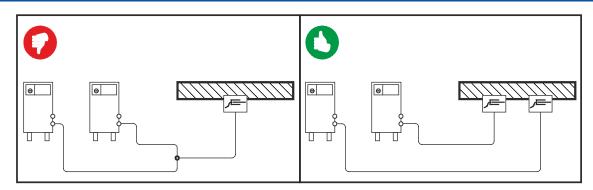


Figure 5-4



Fully unroll welding current leads, torch hose packages and intermediate hose packages. Avoid loops!

Always keep leads as short as possible!

Lay any excess cable lengths in meanders.

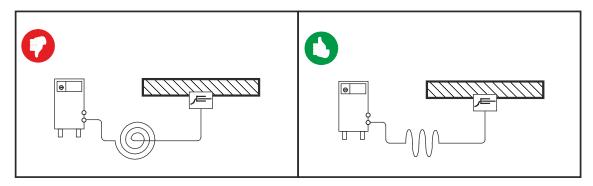


Figure 5-5

Welding torch cooling system



5.7 Welding torch cooling system

5.7.1 General

CAUTION



- Coolant mixtures!
- Mixtures with other liquids or the use of unsuitable coolants result in material damage and renders the manufacturer's warranty void!
 - Only use the coolant described in this manual (overview of coolants).
 - Do not mix different coolants.
 - When changing the coolant, the entire volume of liquid must be changed.

NOTE

- The disposal of coolant must be carried out according to official regulations and observing the relevant safety data sheets (German waste code number: 70104)!
 - Coolant must not be disposed of together with household waste.
 - Coolant must not be discharged into the sewerage system.
 - Recommended cleaning agent: water, if necessary with cleaning agent added.

5.7.1.1 List of coolants

Only the following coolant may be used:

Coolant	Temperature range
KF 23E	- 10 °C to +40 °C



Mains connection

5.8 Mains connection

🚹 DANGER

Hazard caused by improper mains connection!

- An improper mains connection can cause injuries or damage property!
- Only use machine with a plug socket that has a correctly fitted protective conductor.
 - If a mains plug must be fitted, this may only be carried out by an electrician in accordance with the relevant national provisions or regulations!
 - Mains plug, socket and lead must be checked regularly by an electrician!
 - When operating the generator always ensure it is earthed as stated in the operating instructions. The resulting network has to be suitable for operating devices according to protection class 1.

5.8.1 Mains configuration

NOTE

The machine may only be connected to a three-phase system with four conductors and an earthed neutral conductor.

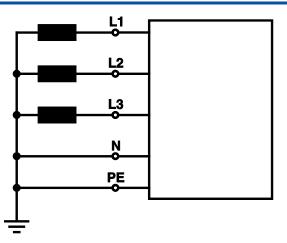


Figure 5-6

Legend		
Item	Designation	Colour code
L1	Outer conductor 1	brown
L2	Outer conductor 2	black
L3	Outer conductor 3	grey
Ν	Neutral conductor	blue
PE	Protective conductor	green-yellow

CAUTION

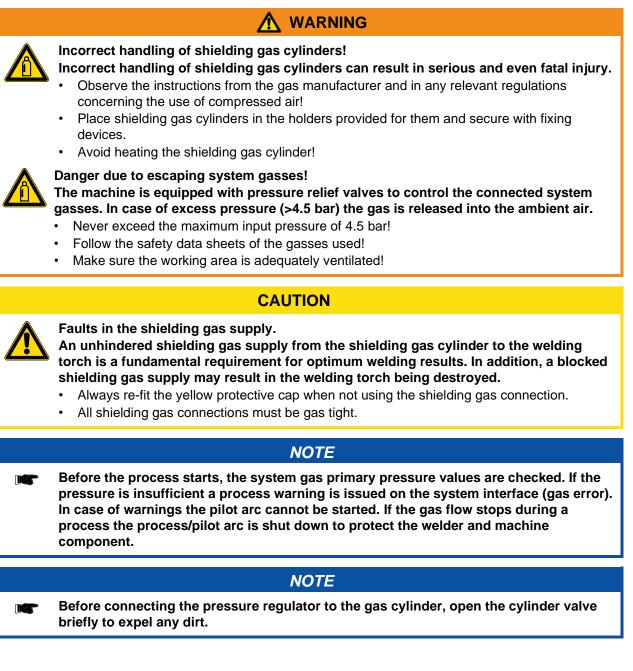
Operating voltage - mains voltage! The operating voltage shown on the rating plate must be consistent with the mains voltage, in order to avoid damage to the machine!

- · For mains fuse protection, please refer to the "Technical data" chapter!
- Insert mains plug of the switched-off machine into the appropriate socket.

System gas connection



5.9 System gas connection





System gas connection

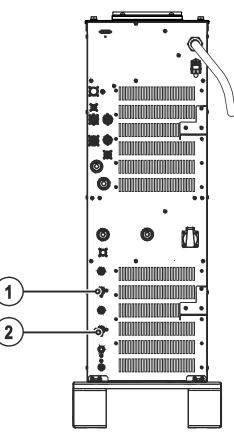
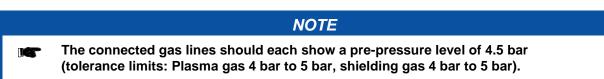


Figure 5-7

ltem	Symbol	Description
1		G1/4" connecting nipple, shielding gas connection
	***	Connection to the pressure reducer
2	(LU)	G1/4" connecting nipple, plasma gas connection Connection to the pressure reducer

- Screw the connection coupling of the plasma gas line onto the G1/4" connecting nipple, plasma gas connection.
- Screw the connection coupling of the shielding gas line onto the G1/4" connecting nipple, shielding gas connection.



Design and function

System gas connection

ewm

5.9.1 Connecting the shielding gas supply

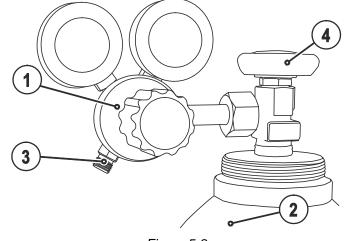


Figure 5-8

ltem	Symbol	Description
1		Pressure regulator
2		Shielding gas cylinder
3		Output side of the pressure regulator
4		Cylinder valve

- Place the shielding gas cylinder into the relevant cylinder bracket.
- Secure the shielding gas cylinder using a securing chain.
- Tighten the pressure regulator screw connection on the gas bottle valve to be gas-tight.
- Screw gas hose connection crown nut onto the output side of the pressure regulator.
- Fit the gas hose and G1/4" crown nut onto the relevant connection on the welding machine, and fit the wire feed unit (if present on this version).

5.9.1.1 Gas test

Operating element	Action	Result
(()	1 x 🖉	Select gas test "Gas pre-flow time (TIG)" signal light is on. Shielding gas flows for approx. 20 seconds. The gas test can be ended immediately by pressing it once more.

5.9.1.2 "Purge hose package" function

Operating element	Action	Result
Ô	5 s 🖉	Select hose package rinsing "Gas pre-flow time (TIG)" signal light flashes. The function is ended by pressing the button again.
		NOTE

If the "Rinse hose package" function is not ended by pressing the "Gas and current parameters" button again, shielding gas will flow until the gas cylinder is empty!



5.10 Welding torch connection

CAUTION

Use of unsuitable coolants results in damage to the welding torch! Unsuitable coolants can cause damage to the welding torch!

• Use only KF 23E coolants (observe temperature range of - 10 °C bis + 40°C).

NOTE

Please note the relevant documentation of the accessory components.

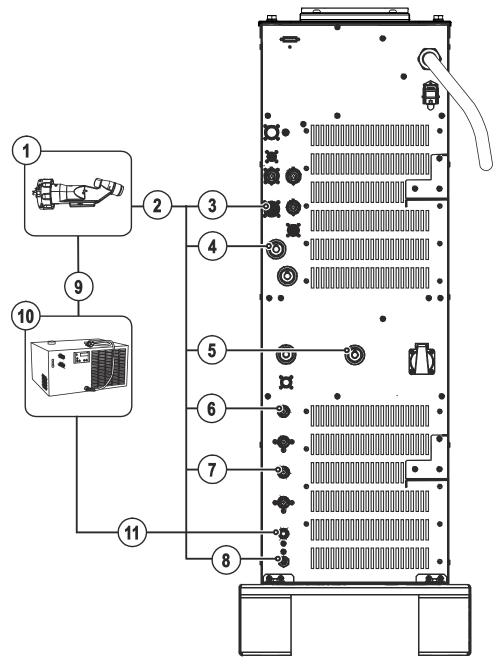


Figure 5-9

Design and function

Welding torch connection



ltem	Symbol	Description
1		Plasma torch
2		Welding torch hose package
3	n	23-pole connection socket (analogue)
	Ų=	Mechanised welding torch connection
4		Connection socket, welding current -
		Welding torch connection
5		Pilot current connection socket
		Plasma welding torch nozzle potential
6		G1/4" connecting nipple, shielding gas, outlet
		Connection to welding torch
7		G1/4" connecting nipple, plasma gas, outlet
		Connection to welding torch
8		Rapid-action closure nipple
		Coolant return from welding torch
9	\bigcirc	Quick connect coupling, blue
	Ur	Coolant supply to the welding torch
10		Cooling unit
11	\cap	Quick connect coupling (red)
		Coolant return to cooling unit

- Insert the 23-pole control lead plug into the 23-pole connection socket (analogue) and lock.
- Insert the welding current plug on the welding torch into the welding current connection socket and lock by turning to the right.
- Insert the plug of the pilot power line into the "+" pilot current connection socket.
- Screw the crown nut on the shielding gas lead gastight to the connecting thread (G1/4").
- Screw the crown nut of the plasma gas line tightly on to the connecting thread (G¼").
- Fit and firmly engage the torch's reverse coolant flow to the quick connect coupling of the welding machine.
- Fit and firmly engage the reverse coolant flow of the reverse cooling unit to the welding machine's quick connect coupling.
- Fit and firmly engage the torch's coolant supply to the quick connect coupling of the reverse cooling unit.



5.11 "Insufficient wire" sensor connection

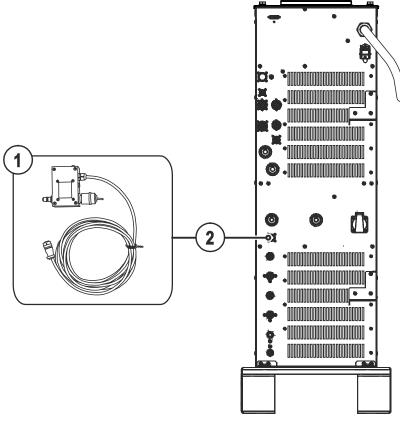


Figure 5-10

Item	Symbol	Description
1		"Insufficient wire" sensor
		A warning is issued as soon as the end of the wire (insufficient wire) is reached. The process will not be shut down.
2	X13	"Insufficient wire" sensor connection
		NOTE

147	The cold wire supply is monitored by the "Insufficient wire" sensor, which is fastened to the wire drum and signals low wire supply in good time. If the wire supply is insufficient
	a process warning is issued on the system interface (wire error). However, this is just a warning; the process will not be shut down.

Design and function

Connecting the wire feed unit



5.12 Connecting the wire feed unit

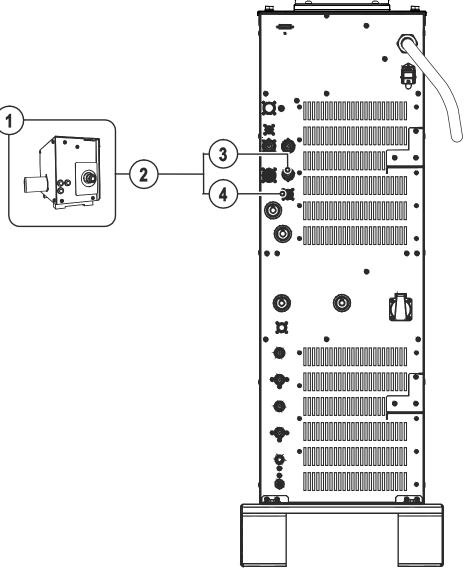


Figure 5-11

Item	Symbol	Description
1		Wire feed unit
2		Control lead assembly
3	8	7-pole connection socket (digital) Wire feed unit connection
4	8	12-pole connection socket (analogue) Wire feed unit connection

- Insert 7-pole plug on the intermediate tube package lead into the 7-pole connection socket and secure with crown nut (the plug can only be inserted into the connection socket in one position).
- Plug the 12-pole cable socket on the intermediate tube package into the 12-pole connector plug and secure using crown nut.



5.13 Hot wire power source connection

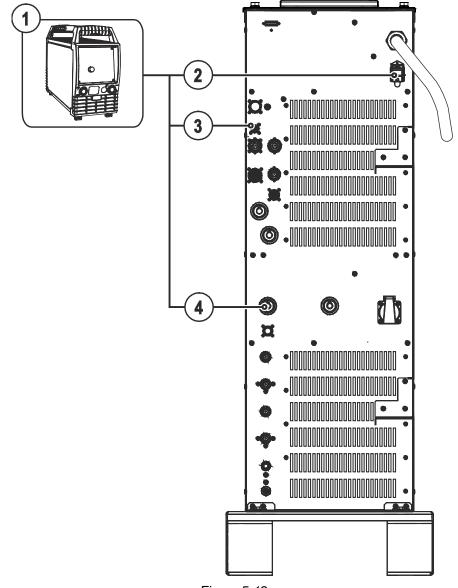


Figure	5-12
	• • =

ltem	Symbol	Description	
1		Hot wire power source	
2		Mains connection, hot wire power source	
		Power supply for hot wire power source	
3	hotWire	Control lead connection, hot wire power source	
		4-pole connection to the hot wire power source	
4	╡╉╸	Connection socket for "+" welding current Connection to TIG power source for hot wire application	

- Insert the 4-pole cable plug of the hot wire power source control lead into the 4-pole connection socket and secure with a crown nut (the plug can only be inserted into the connection socket in one position).
- Push the cable socket for the welding current (TIG hot wire) onto the connector plug (TIG hot wire) and lock by turnng to the right.
- Insert mains plug of the switched-off machine into the appropriate socket on the TIG power source.

Cooling unit connection



5.14 Cooling unit connection

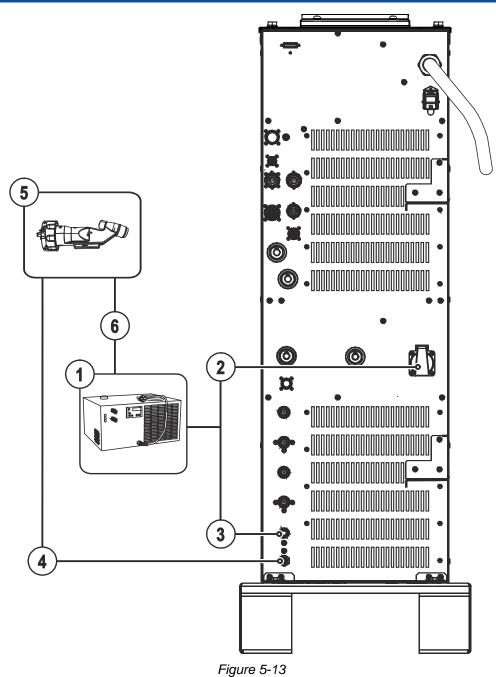
CAUTION

Use of unsuitable coolants results in damage to the welding torch! Unsuitable coolants can cause damage to the welding torch!

• Use only KF 23E coolants (observe temperature range of - 10 °C bis + 40°C).

NOTE

Observe the fitting and connection instructions given in the relevant operating instructions for the cooling unit.



Cooling unit connection



ltem	Symbol	Description
1		Cooling unit
2	Θ	Cooling unit voltage supply Protective contact socket
3	⊖ →	Quick connect coupling (red) Coolant return to cooling unit
4	-	Rapid-action closure nipple Coolant return from welding torch
5		Plasma torch
6	⊖•	Quick connect coupling, blue Coolant supply to the welding torch

- · Connect the cooling unit mains connection cable with an external voltage supply.
- Establish a coolant return from the welding torch to the power source.
- Establish a coolant return from the power source to the cooling unit.
- Establish a coolant forward flow from the cooling unit to the welding torch.

NOTE

Coolant flow monitoring

After switching on the system, monitoring sets in with a time delay of 30 s to allow for the system pressure to build up. The flow rate depends on the torch used. At the moment monitoring is adjusted for use with a torch of type 150A PMC. If the flow rate is less than 1,2 l/min a process warning is issued on the system interface (coolant error). If the flow rate drops below 1,0 l/min an error is generated in the system causing the main and pilot arc to be switched off.

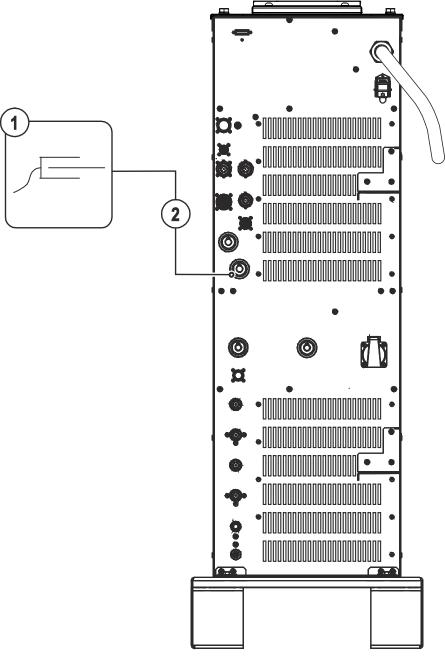
Coolant temperature monitoring

After switching on the system, monitoring sets in with a time delay of 30 s to allow for the system temperature to build up. If the system temperature rises to above 35 °C a process warning is issued on the system interface (coolant error). If the temperature rises to above 42 °C an error is generated in the system causing the main and pilot arc to be switched off.

Design and function Connection for workpiece lead



Connection for workpiece lead 5.15





ltem	Symbol	Description
1	Ч	Workpiece
2	╉	Connection socket, "+" welding current Connection for workpiece lead

Insert the cable plug on the work piece lead into the "+" welding current connection socket and lock by • turning to the right.



TIG Synergic operating principle

5.16 TIG Synergic operating principle

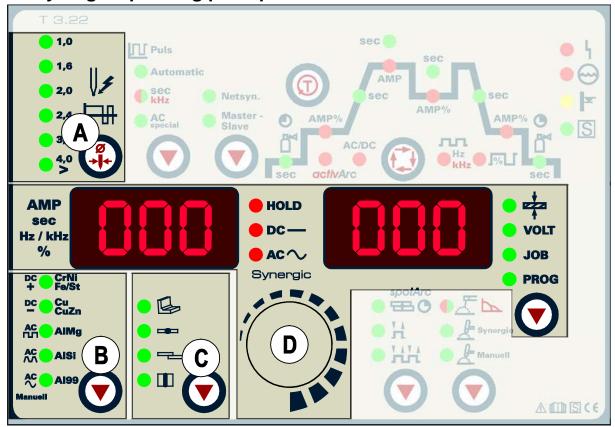


Figure 5-15

The machine is operated according to the TIG Synergic operating principle: The three basic parameters

- tungsten electrode diameter (A),
- material type (B) and
- seam type (C)

are used to select the welding task (JOB).

All welding parameters specified here are the optimum settings for a variety of applications, but they can also be modified individually.

The required welding current can be set as the sheet metal thickness or conventionally as the welding current (D).

The parameters and functions described here can also be programmed by PC using the Tetrix PCT 300 welding parameter software.

The Tetrix machine range has been designed to be very easy and quick to operate, whilst still providing all the functions one could ever need.

TIG Synergic operating principle



5.16.1 Synergic parameter setting in the functional sequence

When setting the welding current, all the necessary welding parameters are adjusted automatically during the functional sequence (see chap. "TIG functional sequences") with the exception of the gas pre-flow time. These welding parameters can also be set in the conventional way if required (regardless of the welding current) (see chap. "Conventional parameter setting in the functional sequence").

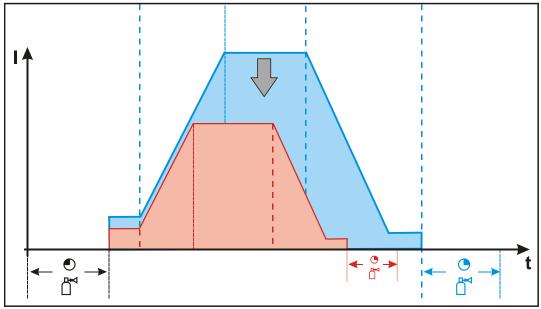


Figure 5-16

5.16.2 Conventional parameter setting in the functional sequence

All welding parameters in the functional sequence can also be adjusted, regardless of the welding current set. This means that if the welding current is changed, the values for the down slope time or gas post-flow time remain unchanged, for example. The welding task still needs to be selected as before using the three basic parameters of tungsten electrode diameter, material type and seam type.

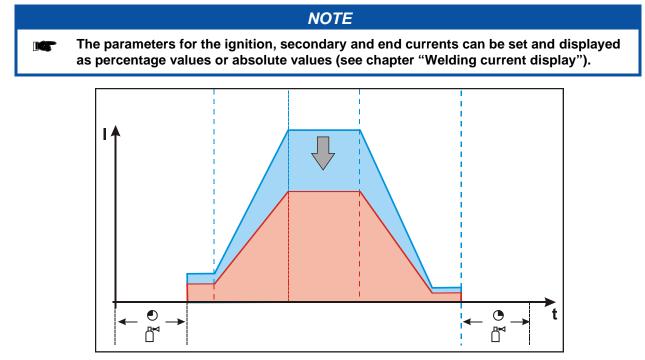


Figure 5-17



Design and function TIG Synergic operating principle

5.16.2.1 Set the operating principle (conventional/synergic)

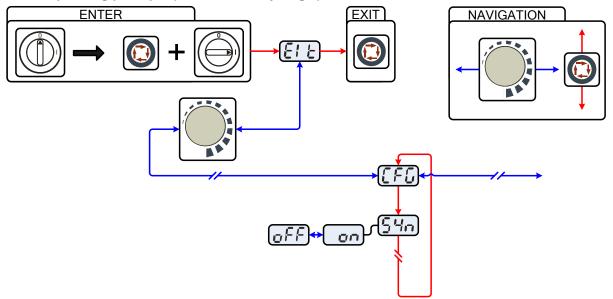


Figure 5-18

Display	Setting/selection			
	Exit the menu			
	J Exit			
	Machine configuration			
	Settings for machine functions and parameter display			
	Operating principle			
חרכן	on = synergic parameter setting (factory setting)			
	off = conventional parameter setting			
	NOTE			
E	NTER (enter the menu)			
•	witch off machine at the main switch			
•	Press and hold the "welding parameters" button and switch the machine on again at the			
	same time.			
N	AVIGATION (navigating in the menu)			
•	Parameters are selected by pressing the "welding parameters" button.			
•	Set or change the parameters by turning the "welding parameter setting" rotary dial.			
EXIT (leave the menu)				
•	Select the "Elt" menu item.			
•	Press the "welding parameters" button (settings will be applied, machine changes to the ready-to-operate status).			

Design and function

ewm

TIG Synergic operating principle

5.16.3 Select welding task

The welding task is selected using the buttons on the machine control on the welding machine. Signal lights (LED) display the welding parameter selection.

NOTE

It is only possible to change the basic welding parameters if:

- No welding current is flowing and
- The key switch (option) is set to position "1".

Operating element	Action	Result
● 上 ● 上 ● Pyracegio ● 上 Hannoti		Select and display welding process.
1,0 1,8 2,0 2,4 4 3,2 4,0 4,0 4,0 4,0	Æ	 Select and display electrode diameter / ignition optimisation. TIG - Synergic: Select electrode diameter (ignition optimisation is determined automatically). TIG - Manual: Select ignition optimisation.
PC ← CrNI P ← Cult Cult Cult Aling Aling Aling Aling Manusel	Ø	 Select and display material type or welding current polarity. TIG - Synergic: Select material type (welding current polarity is determined automatically). TIG - Manual: Select welding current polarity.
		Select and display seam type.
spotArc H H H H H		Select and display operating mode.

5.16.4 Select welding current

The user has two options for setting the required welding current:

- Using the sheet metal thickness
- · Directly as welding current

The welding current is displayed in the left-hand display. The "Material thickness" parameter can be selected in the right-hand display.

Control element	Action	Result	Display (right)
• • • • • • • • • •	X x Pr	Press button until signal light Material Thickness comes on.	Material thickness in mm is displayed.
		Set welding current or sheet metal thickness.	Welding current and sheet metal thickness are displayed



5.16.5 Welding data display

The following welding parameters can be displayed before (nominal values), during (actual values) or after welding (hold values):

"Left-hand display"						
Parameter	Before welding (nominal values)	During welding (actual values)	After welding (hold values)			
Welding current	•	•	•			
Parameter times	•	-	-			
Frequency, balance	•	-	-			
Parameter currents	•	-	-			
	"Right-hand display"					
Material thickness	•	-	-			
Welding voltage	•	•	•			
JOB number	•	-	-			
Program number	•	-	-			

After welding the hold values are displayed. When changes are made to the settings (e.g. welding current) after welding, the display switches to the relevant nominal values.

The right-hand display automatically switches over to the material thickness after approx. 4 seconds.

If the "Program number" signal light is on in addition to the "Material thickness" signal light, the user is in program mode (programs 1-15, see chap. "Welding programs").

If the "JOB number" signal light is on in addition to the "Material thickness" light, the user is in a JOB in the free memory (JOBs 128 to 256, see chap. "Creating a new JOB in the free memory").

5.16.5.1 Welding parameter setting

During the welding parameter setting process, the parameter value being set is displayed on the left-hand display. The right-hand display shows the "Factory setting" or a variation of it upwards or downwards. Displays, e.g. when setting the ignition current, and their meanings:

Display	Meaning of the symbols shown in the right-hand display		
	Increase parameter value	To restore the factory settings.	
20 -0-	Factory setting	Parameter value is on the optimum setting	
30 [')	Reduce parameter value	To restore the factory settings.	

Design and function

TIG Synergic operating principle

5.16.6 Arc ignition

The pilot arc is activated/deactivated by pressing the "Pilot arc on/off" push-button.

After activating the pilot arc, the pre-set gas pre-flow time runs, the pilot arc current ignites without workpiece contact between the electrode and nozzle, and the control lamp in the push-button illuminates.

CAUTION



Oxidation of the tungsten electrode! To protect the tungsten electrode against oxidation carry out the following actions before switching off the power source:

- Switch off the pilot arc and wait for the gas post flow time to elapse!
- Do not switch off the machine while the arc is still burning!

NOTE

On delivery, the Hilibo current on the machine is preset to 10A. The majority of applications are covered by this current setting. If required, the Hilibo current can be adjusted individually using the PC300.NET software (5A to 80A).



Please note the relevant documentation of the accessory components.

5.16.7 Optimising the ignition characteristics for pure tungsten electrodes

This parameter can be used to improve the ignition characteristics of "pure tungsten electrodes", for example. The parameter is a %-value (factory-set to 20) and is changed across all JOBs.

Control element	Action	Result	Display
	1 x 🖭	Select Ignition Characteristics parameter The signal lights for the selected electrode diameter and ignition current AMP% flash for approx. 5 seconds. The parameter value can be optimised on the rotary transducer during this time.	-0- 05
		Set parameter value Increase parameter value: more ignition power Reduce parameter value: less ignition power	30 [-0

5.16.8 TIG automatic cut-out

	NOTE
J.C.	 If the arc does not ignite after starting or if the arc is interrupted when the torch is moved away, an automatic cut-out occurs after 5 sec. The HF, gas and open circuit voltage (power unit) are switched off. If RINTX1x or BUSINTX1x are in use the automatic cut-out is regulated by the settings made with the software PC300.net.



5.16.9 Optimal and fast spherical cup formation

A conically ground tungsten electrode (approx. 35°) is generally required to form an ideal spherical cup.				
Operating element	Action	Result		
DC CrNi FeiSt DC CuZn AC AIMg AC AISI AC AISI Manuell		Select AC/DC welding with appropriate material:AIMgaluminium and magnesium alloys.AISialuminium and silicon alloys orAI99aluminium 99%		
Ignition optimisation selection The signal light of the selected needle diameter starts flashing.				
Image: Interster indentify Im				
NOTE				
 Use a sample workpiece. Ignite arc with HF ignition (non-contact) and form required spherical cup for the application in question. 				

Welding task definition



5.17 Welding task definition

The user defines the welding tasks using JOB numbers.

Each JOB number stores all the parameters relating to the welding task.

The user can either load an existing JOB, load an existing JOB and change it, or define a completely new JOB via the various interfaces.

The welding task or JOB is defined using the following parameters:

Basic parameters

The JOB number is defined using the four basic welding parameters: welding process, material type, wire diameter and seam type.

Program sequence

Other welding parameters, such as parameters for the start program, secondary program or end program and the gas pre-flow time, slope times and many more are preset for a variety of applications, but can be modified where required. On the various interfaces, the most important welding parameters are displayed directly and can be modified where required.

Operating point

The operating point can be set via up to 15 (PROG 1 to PROG 15) freely definable programs using a robot interface (RINT X12/BUSINT X11), for example.

• The welding current, operating mode and pulse function are stored in each program. These program parameters can be set on a PC or the tablet PC RC 300 using the PC 300 welding parameter software. The program number is selected by the robot control.

The digital system calculates the process parameters required, such as the welding current, welding voltage and pulse current according to the operating point specified.

Operating mode

Non-latched or special non-latched (start, main and end program).

These parameters are predefined by the robot control via robot interface RINT X12 or BUSINT X11 (see the relevant interface documentation).

Welding type

Pulse or standard welding.

This parameter setting is specified by the robot control via the RINT X12 or BUSINT X11 robot interface (see documentation in the relevant interface description).



5.18 Protecting welding parameters from unauthorised access

To protect against unauthorised or unintentional adjustment of the welding parameters on the machine, the control input can be locked with the aid of a key switch.

- Key position 1 = All parameters can be set
- Key position 0 =
- Only the following operating elements are functional:
 - "Operating mode" button
 - "Welding parameter setting" rotary transducer
 - "Display switching" button
 - "TIG pulse welding"/"Select activArc" button
 - "Select welding parameters" button
 - "Gas test" button

5.19 Welding programs

The welding machine has 16 programs, which can be accessed during the welding process, e.g. using an up/down torch.

In each selected welding task (JOB), see the "Selecting the welding task" chapter, 16 programs can be set, saved and accessed. In program "0" (default setting), the welding current can be set infinitely across the whole range. In programs 1–15, 15 different welding currents can be defined.

Operating mode and pulse function can also be defined for programs 1–15, if the connected RINT X12 or BUSINT X11 interface is in JOB mode. If the interfaces are not in JOB mode, operating mode and pulse function are predefined by the interfaces.

Example:

Program number	Welding current	Operating mode	Pulse function
1	80 A	Non-latched	Pulses on
2	70 A	Latched	Pulses off

The operating mode cannot be changed during the welding process. If the process is started with program 1 (non-latched operating mode), program 2, despite being set to latched operating mode, will apply the setting of start program 1 until the end of the welding process.

Pulse function (pulses off, pulses on) and welding currents will be applied from the relevant programs.

NOTE

Changes made to the other welding parameters during the course of the program have the equivalent effect on all programs.

Any change to the welding parameters is saved immediately in the JOB!

Welding programs

5.19.1 Selection and adjustment

Setting welding programs using the welding machine control

Operatin g element	Action	Result	Display
• volt • Job • PROG		Press button until signal light PROG comes on.	Welding current (left) and program no. (right)
		Select or retrieve program no., e.g. no. 1	
ароналс • Н • Н • НН		Set operating mode (can be specified separately for each program).	No change
	<u>P</u>	Press until a "P" for program no. is displayed in the left- hand section of the right-hand display. Any parameter can be selected and changed in the function sequence. The changes are transferred to all other programs in the same way.	50 P 1
		Set welding current for the corresponding program (e.g.: 75 A in program 1).	75) P 1

NOTE

When connecting a potentiometer torch or up/down torch or operating a standard torch in up/down mode, the program changeover to the welding machine control is blocked!

5.19.2 Specifying max. no. of accessible programs

NOTE This function can be used to specify the maximum number of programs which can be called up (only applies to the welding torch). According to the factory setting, all 16 programs can be called up. If necessary these can be limited to a specific number. To limit the number of programs, the welding current needs to be set to 0A for the next, unused program. For example, if only programs 0 to 3 are being used, the welding current is set to 0A in program 4. A maximum of programs 0 to 3 can then be called up on the welding torch.





Welding programs

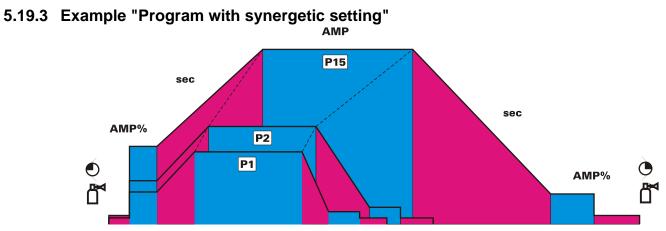
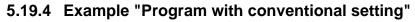
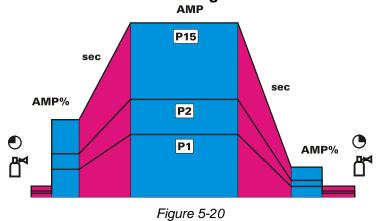


Figure 5-19





5.19.5 Accessories for switching over programs

The user can change, retrieve and save programs using the following components.

	Program	ns
Component	create and change	call up
Welding machine control	16	16
PC with PC 300 welding parameter software	16	16
Tablet PC RC 300 with PC 300 welding parameters	16	16
Tetrix RINT robot interface	-	16
BUSINT X10 industrial bus interface	-	16



5.20 Organising welding tasks (Mode "JOB Manager")

 NOTE

 Welding jobs (JOBs) / programs are organised (configured, managed, created) using the parameterisation software PC300.Net. JOBs are switched with an interface (e.g., RINT X12).

 Please note the relevant documentation of the accessory components.

The JOB Manager can be used to load, copy or save JOBs.

A JOB is a welding task defined using the 4 main welding parameters

- welding process,
- material type,
- electrode diameter and
- seam type.

One program sequence can be defined in each JOB.

Up to 16 programs (P0 to P15) can be set in each program sequence.

The user has a total of 249 JOBs available. 121 of these JOBs are pre-programmed. A further 128 JOBs can be freely defined.

A distinction is made between two memory sectors:

- 121 factory-set, pre-programmed, permanent JOBs. Permanent JOBs are not loaded but are defined by the welding task (each welding task is permanently assigned a JOB number).
- 128 freely definable JOBs (JOBs 129 to 256)

NOTE

After carrying out any of the actions described, the machine switches back to the default parameters such as current and voltage. To ensure that all the changes are active, the welding machine should only be switched off after 5 seconds have elapsed.

5.20.1 Explanation of symbols on the display

Display	Meaning
<u>Laj</u>	Load JOB
د منا	Сору ЈОВ
(J	Reset JOB
<u>r E.A</u>	Reset all JOBs



5.20.2 Creating a new JOB in the memory or copying a JOB

NOTE It is normally possible to adjust all 256 JOBs individually. However, it is a good idea to assign specific JOB numbers in the free memory (JOB 128 to 256) for specific welding tasks.

Copying a pre-defined welding task from the fixed memory (JOBs 1 to 128) to the free memory (JOBs 129-256):

		ΝΟΤΕ	
jier De	Define welding task which most closely matches the required application.		
Operating element	Action	Result	Display
volt Job Prog	x x 💁	Select JOB Manager mode	Press until the "VOLT" signal light is on
• $\frac{1}{2}$ • Volt • Job • Prog	2 sec. 💽	Select JOB Manager mode	LaJ []
• et a • volt • Job • Prog	1 x 🖉	Switch from "Load JOB" to "Copy JOB"	د منا
	C)	Select the required JOB number using the rotary transducer (e.g. 150)	cai (150)
VOLT JOB PROG	1 x 座	JOB has been copied to the free memory, machine switches back to Display mode. The JOB can be modified individually.	Current value and JOB number displayed



5.20.3 Loading an existing JOB from the free memory

Operating element	Action	Result	Display
• eta • Volt • Job • PRog	x x 💇	Select JOB Manager mode	Press until the "VOLT" signal light is on
Volt Job PROG	2 sec.	Select JOB Manager mode	LaJ
		Select the required JOB number using the rotary transducer (e.g. 150)	Lai [150]
• eta • Volt • JOB • PROG	1 x 💁	JOB loaded, machine switches back to Display mode. The JOB can be customised as required.	Current value and JOB number displayed

5.20.4 Resetting an existing JOB to the factory setting (Reset JOB)

Operating element	Action	Result	Display
• # • Volt • JoB • PROG	x x 💽	Select JOB Manager mode	Press until the "VOLT" signal light is on
• E • VOLT • JOB • PROG	2 sec. 💽	Select JOB Manager mode	[ad]
• E • Volt • Job • PROG	2 x 💽	Switch from "Load JOB" to "Reset JOB"	r E.J []
		Select the required JOB number using the rotary transducer (e.g. 150)	r E.J [150]
• E • Volt • Job • PRog	1 x 💽	JOB reset to factory settings, machine switches back to Display mode.	Current value and JOB number displayed



.5	Resetting	JOBs 1-128	8 to the factory setting (Reset All JOBs)	_
	Operating element	Action	Result	Display
	• tore tore tore tore tore tore tore tore	x x 💽	Select JOB Manager mode	Press until the "VOLT" signal light is on
	• eta • volt • Job • PRog	2 sec. 🔎	Select JOB Manager mode	LaJ
	• ± • volt • JoB • PRog	3 x 座	Switch from "Load JOB" to "Reset All JOBs"	<u>- E.A</u>]
			 ON = Reset all JOBs to factory settings OFF = Do not reset JOBs 	rEA on
	• = = = = = = = = = = = = = = = = = = =	1 x 🖉	All JOBs reset to factory settings, machine switches back to Display mode.	Current value and JOB number displayed

5.20.5 Resetting JOBs 1-128 to the factory setting (Reset All JOBs)

5.20.6 Exit JOB Manager without changes

The user is in the JOB manager menu and wants to exit without making any changes:

Operating element	Action	Result	Display
• eta • Volt • JoB • PROG	2 sec. 💽	Machine switches back to Display mode The JOB can be adjusted individually.	Current value and JOB number displayed

Interfaces



5.21 Interfaces

5.21.1 Connecting the robot interface / industrial bus interface

CAUTION



Damage due to the use of non-genuine parts! The manufacturer's warranty becomes void if non-genuine parts are used!

- Only use system components and options (power sources, welding torches, electrode holders, remote controls, spare parts and replacement parts, etc.) from our range of products!
- Only insert and lock accessory components into the relevant connection socket when the machine is switched off.



Damage due to incorrect connection!

Accessory components and the power source itself can be damaged by incorrect connection!

- Only insert and lock accessory components into the relevant connection socket when the machine is switched off.
- Comprehensive descriptions can be found in the operating instructions for the relevant accessory components.
- Accessory components are detected automatically after the power source is switched on.

The interfaces can be operated directly on the power source in a separate interface casing or externally, e.g. in a robot control cabinet or via a data cable.



Interfaces

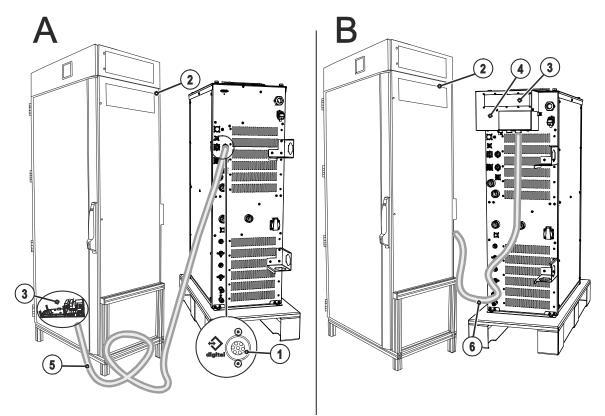


Figure 5-21

ltem	Symbol	Description
1		7-pole connection socket (digital)
		For connecting digital accessory components
2		Switching cabinet
3		Robot interface / Industrial bus interface
4		Interface casing ATCASE
5		Connection cable, 7-pole
		Connection between switching cabinet and power source
6		Connection lead
		Connection between interface casing and switching cabinet

5.21.1.1 RINT X12 robot interface

The standard digital interface for mechanised applications (optional, retrofitting on the machine or external fitting by the customer)

Functions and signals:

- Digital inputs: start/stop, operating modes, JOB and program selection, inching, gas test
- Analogue inputs: control voltages, e.g. for welding performance, welding current, etc.
- Relay outputs: process signal, ready for welding, system composite fault, etc.

5.21.1.2 BUSINT X11 industrial bus interface

The solution for integration into mechanised production lines, with for example

- PROFIBUS
- CAN-OPEN, CAN DEVICENET
- ETHERNET IP
- PROFINET

TEST

Interbus systems with copper and optical fibre connection (FSMA/Rugged Line)

NOTE

Only one variant can ever be operated at any one time.

Design and function

Interfaces



5.21.2 Connecting the PC 300.net welding parameterisation software

Create all welding parameters quickly on the PC and easily transfer them to one or more welding machines (accessories, set consisting of software, interface, connection leads)

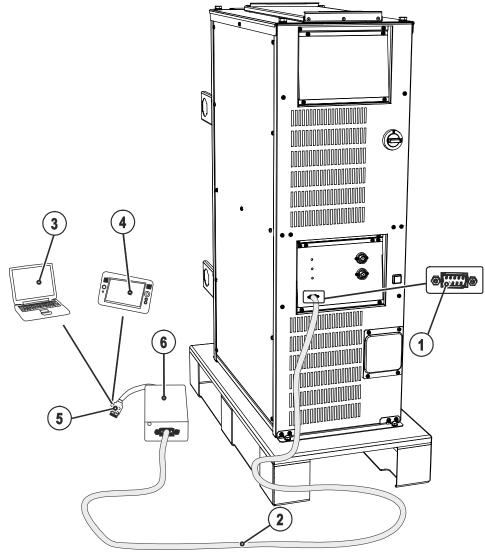


Figure 5-22

ltem	Symbol	Description
1		PC interface, serial (D-Sub connection socket, 9-pole)
2		Connection cable, 9-pole, serial
3		Windows PC
4		RC300 tablet PC
5		USB connection
6		SECINT X10 USB

CAUTION



Equipment damage or faults may occur if the PC is connected incorrectly! Not using the SECINT X10USB interface results in equipment damage or faults in signal transmission. The PC may be destroyed due to high frequency ignition pulses.

Interface SECINT X10USB must be connected between the PC and the welding machine!
The connection must only be made using the cables supplied (do not use any additional extension cables)!



5.21.3 Connecting the Q-DOC 9000 V2.0 welding data documentation software

(Accessories: Set consisting of software, interface, connection leads) The ideal tool for welding data documentation of, for example: welding voltage and current, wire speed and motor current.

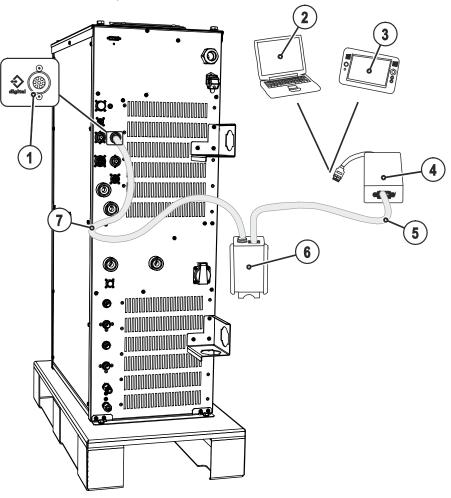


Figure 5-23

ltem	Symbol	Description
1	\Rightarrow	7-pole connection socket (digital) For connecting digital accessory components
2		Windows PC
3		RC300 tablet PC
4		SECINT X10 USB
5		Connection cable, 9-pole, serial
6		PCINT X10
7		Connection cable, 7-pole Connection between switching cabinet and power source

CAUTION



Equipment damage or faults may occur if the PC is connected incorrectly! Not using the SECINT X10USB interface results in equipment damage or faults in signal transmission. The PC may be destroyed due to high frequency ignition pulses.

Interface SECINT X10USB must be connected between the PC and the welding machine!
The connection must only be made using the cables supplied (do not use any additional extension cables)!



5.21.4 Connecting the WELDQAS welding data monitoring and documentation system

Network-compatible welding data monitoring and documentation system for digital power sources.

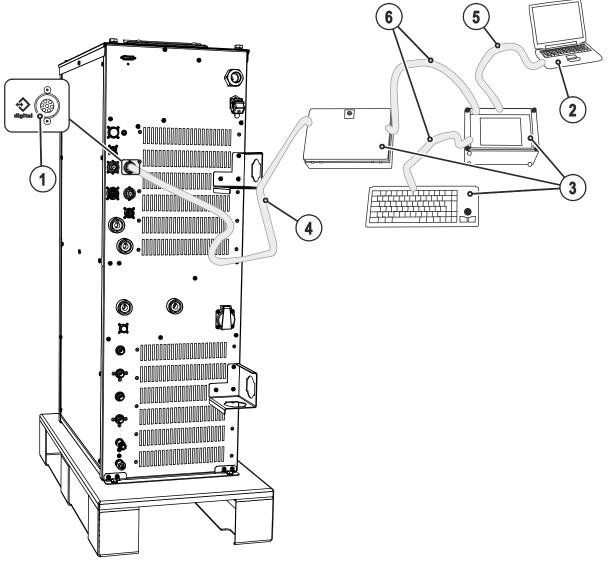


Figure 5-24

ltem	Symbol	Description
1		7-pole connection socket (digital)
_	\sim	For connecting digital accessory components
2		Windows PC
3		WELDQAS welding data monitoring and documentation system
4		Connection cable, 7-pole
		Connection between switching cabinet and power source
5		Integration option of WELDQAS into existing network systems via network cables
6		Connection cable included as standard with WELDQAS



Interfaces

5.21.5 Automation interface



No function of the external interrupt equipment (emergency stop switch)! If the emergency stop circuit has been realised using an external interrupt equipment via the interface for automated welding, the machine must be configured for this setup. If this is not observed, the power source will ignore the external interrupt equipment and will not shut down!

WARNING

Disconnect jumper 1 on PCB T320/1 (Tetrix) or M320/1 (Phoenix / alpha Q)!

CAUTION



Equipment damage due to unshielded control leads! Unshielded control leads can cause damage to the power source and accessory components.

• Use shielded control leads only.

The welding power sources feature a very high safety standard.

This safety standard is also maintained when peripheral equipment is connected for mechanised welding, if this peripheral equipment meets the same criteria, particularly with regard to isolation from the mains supply.

This is guaranteed by the use of transformers conforming to VDE 0551.

The welding machines are equipped for mechanised operation as standard.

For the simplest possible mechanised applications, control inputs and galvanically isolated relay contacts are available on the interface for mechanised welding.

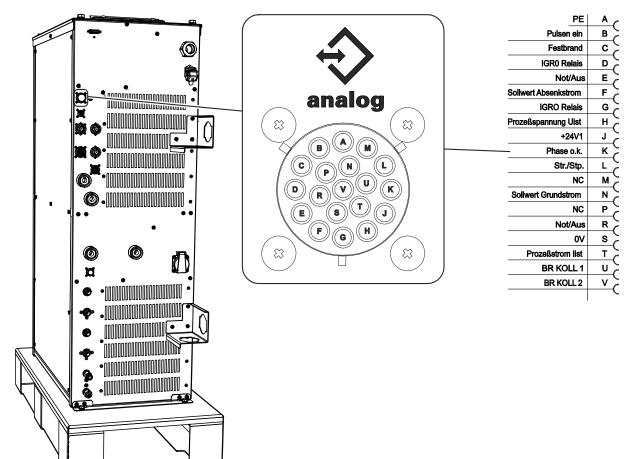


Figure 5-25

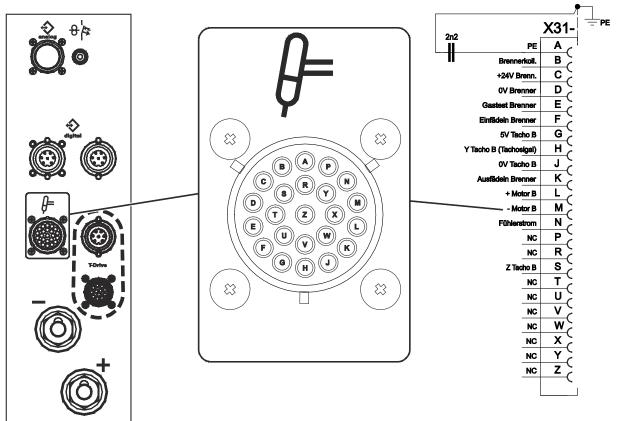


19-pole pin assignment for interface for automated welding (X6):

Pin	Signal form	Signal name circuit diagram	Function	
Α	Output	PE	Connection for cable screen	
В	Input	PULSING ON	Thermal pulse mode up to max. 50 Hz, fixed balance of 50%	
С	Output	Sticking	Analysis signal to detect sticking of the filler wire to the workpiece 24 V = sticking	
D	Output	IGRO RELAY	Current flows signal I > 0 Contact closed = welding current flowing (forms contact with signal G)	
E	Input	EMERGENCY STOP	Emergency stop for higher level shutdown of the power source. To use this function, jumper 1 must be unplugged on PCB T320/1 in the welding machine. Contact open = welding current switched off	
F	Input	INOMINAL LOW	Pilot voltage default for secondary current, $0-10 V (0 V = I^{min}/10 V = I_{max})$	
G	Output	IGRO RELAY	Current flows signal I > 0 Contact closed = current flows (forms contact with signal D)	
Η	Output	UACTUAL	Welding voltage, measured on pin S, $0-10 \vee (0 \vee = 0 \vee, 10 \vee = 100 \vee)$	
J	Input	+24 V1	24 V voltage reference. Supplied by BUSINT X11.	
K	Output	Phase OK	Signal to detect a failed network phase. Analysed by BUSINT X11.	
L	Input	START/STOP	Start/stop of welding current, corresponds to torch trigger. Only available for non-latched operating mode. +15 V = start, 0 V = stop	
М		NC		
N		Basic current nominal value		
Р		NC		
R	Input	EMERGENCY STOP	Emergency stop for higher level shutdown of the power source. To use this function, jumper 1 must be unplugged on PCB T320/1 in the welding machine. Contact open = welding current switched off	
S	Output	0 V	Reference potential	
Т	Output	I actual	Welding current, measured on pin S; 0-10 V (0 V = 0 A, 10 V = 1000 A)	
U	Input	BR. KOLL: 1	Emergency shutdown for anticollision device +24 V	
V	Output	BR. KOLL. 2	Emergency shutdown for anticollision device	



5.21.6 Connection socket automation torch





Connection socket 23-pole Automation torch:

Pin	Signal shape	Signal name	designation	
Α	Output	PE	Connection for cable screen	
В	Input	Brennerkoll.	Emergency shut-down for anticollision device	
С	Output	+24V Brenn.	Emergency shut-down for anticollision device +24 V	
D	Output	0V Brenner*	GND for torch speedometer	
E	Input	Gastest Brenner*	Gas test push-button from torch	
F	Input	Einfädeln Brenner*	Inching push-button from torch	
G	Output	5V Tacho B	Torch Vcc speedometer	
Н	Input	Y Tacho B (Tachosignal	Speedometer signal input from torch	
J	Output	0V Tacho B	GND for torch speedometer	
K		Ausfädeln Brenner*	Reverse inching push-button from torch	
L	Output	+ Motor B	Motor output +	
М	Output	- Motor B	Motor output -	
N	Output	Fühlerstrom	Sensor current output for cold wire	
P-R		NC	not used	
S	Input	Z Tacho B	Speedometer signal duct Z	
T-Z		NC	not used	

*Feature only available for the cold wire versions.

Interfaces



5.21.7 Sensor current

The sensor current is transferred via the connection socket of the automated welding torch.

At the torch, the signal has to be connected to the conducting part of the cold wire feeder. This means outside the welding process an electric potential is active which detects sticking when the feeder or wire has contact with the workpiece at the end of the process.

If the power source is used in combination with a TIG torch please note that the torch electrode having contact with the workpiece cannot be detected.

NOTE

At present, sticking detection is only possible with a dedicated interface which analyses the corresponding "sticking" signal at the 19-pole interface for automated welding. The usual sticking detection of standard interfaces (RINT X12 and BUSINT X11) does not work with this system type.



5.22 Advanced settings

5.22.1 Setting slope times for secondary current AMP% or pulse edges

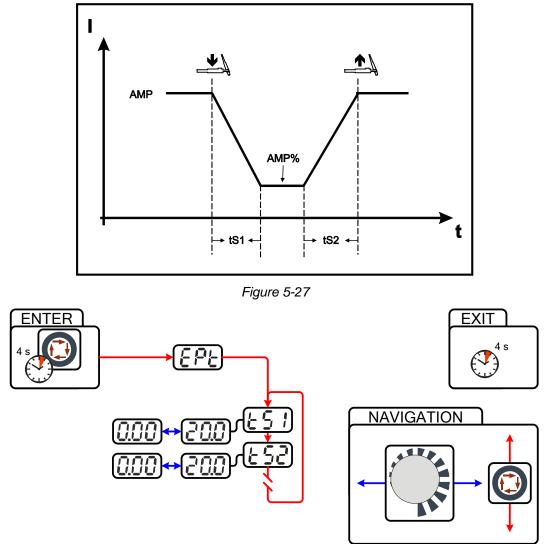
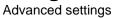


Figure 5-28

Display	Setting/selection	
EPE Expert menu		
<u> </u>	Slope time tS1 (main current to secondary current) Setting: 0.00 s to 20.0 s (factory setting 0.00 s)	
<u> </u>	Slope time tS2 (secondary current to main current) Setting: 0.00 s to 20.0 s (factory setting 0.00 s)	





5.22.2 Welding current display (ignition, secondary, end and hotstart currents)

The welding currents for secondary current, ignition current and end current (expert menu) can be displayed as percentages or absolute values on the machine display.

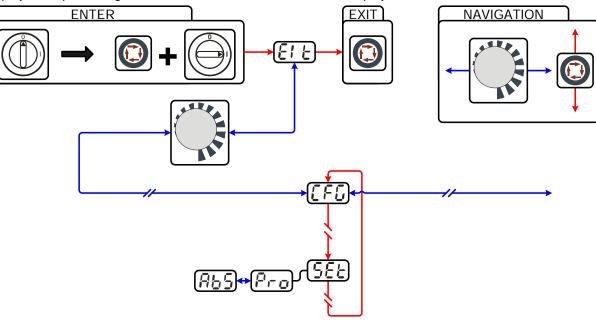


Figure 5-29

Display	Setting/selection		
	Exit the menu		
	Exit		
	Machine configuration		
	Settings for machine functions and parameter display		
	Welding current display (ignition, secondary, end and hotstart currents)		
	 Pro = welding current display as a percentage of the main current 		
	 Abs = absolute welding current display (factory setting) 		



5.23 Menus and sub-menus on the machine control

5.23.1 Direct menus (direct access to parameters)

Functions, parameters and their values can be accessed directly, e.g. can be selected by pressing a button once.

5.23.2 Expert menu (TIG)

- - EXIT (leave the menu)
 - After 4 s, the machine will return automatically to the ready-to-operate status.

The expert menu includes functions and parameters which are either not set on the machine control, or which do not require regular setting.

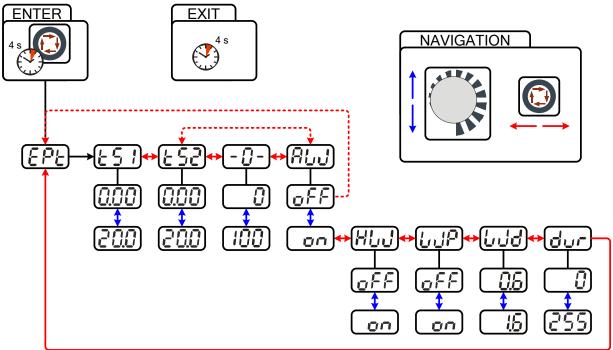


Figure 5-30

Design and function Menus and sub-menus on the machine control



Display	Setting/selection
EPE	Expert menu
	Slope time tS1 (main current to secondary current)
	Setting: 0.00 s to 20.0 s (factory setting 0.00 s)
	Slope time tS2 (secondary current to main current)
	Setting: 0.00 s to 20.0 s (factory setting 0.00 s)
	activArc parameter
	Parameter can also be set after activating TIG activArc welding.
	Display shown = factory setting.
RUJ	Filler wire process (cold/hot wire)
	• on = filler wire activated
	off = filler wire deactivated (factory setting)
HLJ	Hot wire process (start signal for hot wire power source)
	on = hot wire activated
	off = hot wire deactivated (factory setting)
lu JP	Wire/pulse function (wire feed characteristics when using TIG pulses)
	The wire feeding can be disabled during pulse pauses (not in case of pulse
	automatic or kHz pulses).
	• on = wire feeding switched off during pulse pause
	off = wire feeding switched on during pulse pause (ex works)
l led	Filler wire diameter (manual setting)
	Setting of the wire diameter from 0.6 mm to 1.6 mm.
	The character "d" preceding the wire diameter on the display (d0.8) indicates a pre- programmed characteristics (operating mode KORREKTUR).
	If there is no characteristics for the selected wire diameter, the parameters have to be set manually (operating mode MANUELL).
	For information on how to select the operating mode, refer to the chapter "Selecting the wire feed speed (KORREKTUR / MANUELL)".
	Wire return
Øur	 Increase value = more wire return
	Reduce value = less wire return
	Parameter can also be set after connecting a TIG cold wire feed unit. Setting: 0 to 255
	(factory setting 50).



5.23.3 Machine configuration menu

NOTE

ENTER (enter the menu)

- Switch off machine at the main switch
- Press and hold the "welding parameters" button and switch the machine on again at the same time.

NAVIGATION (navigating in the menu)

- Parameters are selected by pressing the "welding parameters" button.
- Set or change the parameters by turning the "welding parameter setting" rotary dial.

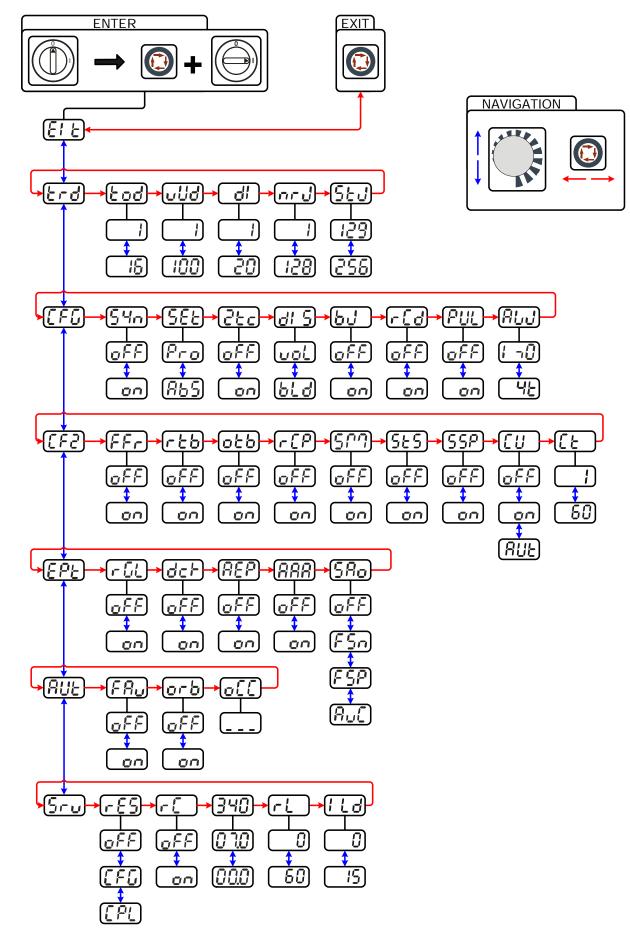
EXIT (leave the menu)

- Select the "Elt" menu item.
- Press the "welding parameters" button (settings will be applied, machine changes to the ready-to-operate status).

Design and function

Menus and sub-menus on the machine control









Display	Setting/selection
	Exit the menu
<u> </u>	Exit
	Torch configuration menu
<u>trd</u>	Set welding torch functions
	Torch mode (factory setting 1)
tod	
	Up-/Down speed
	Increase value = rapid current change (factory setting 10)
<u> </u>	Reduce value = slow current change
dl	Setting the first increment
	Setting: 1 to 20 (factory setting 1)
	Get JOB number
	Set maximum selectable jobs (setting: 1 to 128, factory setting 10).
	Additional parameter after activating the BLOCK JOB function.
Sed	Start JOB
	Set first JOB to get (setting: 129 to 256, factory setting 129).
	Machine configuration
	Settings for machine functions and parameter display
<u> 54a</u>	 Operating principle on = synergic parameter setting (factory setting)
	 off = conventional parameter setting
	Welding current display (ignition, secondary, end and hotstart currents)
566	 Pro = welding current display as a percentage of the main current (factory setting)
	Abs = absolute welding current display
	Non-latched operation (C version)
<u>2tc</u>	• on = on
	• off = off (factory setting)
	Setting for the primary setpoint value display
<u>c' io</u>	Defines the priority display for setpoint values:
	bld = panel thickness
	 vol = welding voltage (factory setting)
	RINT X12, JOB control for automation solutions
	• on = on
	off = off (factory setting)
r[d	Power display switching (MMA)
	on = actual value display
	off = setpoint value display (factory setting)
PUL	Pulses in the upslope and downslope phases
	The function can be switched on or off
ALJ	 additional wire welding, operating mode l>0 = filler wire mode for automated applications,
	wire is conveyed when current flows
	 2t (factory setting) to 4t = operating mode non-latched to latched
	Machine configuration (part two)
[573]	Settings for machine functions and parameter display
	Ramp function Remote control RTF 1
FFr	The ramp function can be switched on and off
	Kalottenbildung mit Remote control
<u>rtb</u>	• on = on (ex works)
	• off = off
	Tungsten balling (old variant)
otb	• on = on
	• off = off (ex works)

Design and function Menus and sub-menus on the machine control



Display	Setting/selection
	Welding current polarity switching
	 on = polarity switching at the RT PWS 1 19POL remote control (ex works) aff a polarity switching at the worlding matching control.
	off = polarity switching at the welding machine control
5177	spotMatic Variation of operation mode spotArc, ignition with workpiece contact
, ,	• $on = on$
	 off = off (factory setting)
	Short spot time
	Setting of 5999 ms (1-ms steps)
Γςρ	Setting process activation
	 on = Separate process activation: The welding process has to be reactivated for every arc ignition by pressing the torch
	trigger.
	 off = Permanent process activation:
	The welding process is activated by pressing the torch trigger once. The following arc
	ignitions are initiated by shortly touching the tungsten electrode against the
	workpiece. Torch cooling mode
	AUt = automatic operation (ex works)
	 on = permanently switched on
	off = permanently switched off
	Water block pre-flow time
	Setting 1–60 min. (ex works 5)
EPE	Expert menu
r GL	AC mean value controller
	• on = on (factory setting)
	off = off Constant on the formulation of t
dch	 Switching option for welding current potential (dc+) with TIG DC off = Select option for TIG DC+ is blocked (factory setting). Serves to protect the
	tungsten electrode from being destroyed.
	• on = Polarity can be selected freely
	Reconditioning pulse (spherical cap stability)
AEP	 on = function on (factory setting)
	off = function off
AAA	activArc voltage measuring
	 on = function on (factory setting) off = function off
	Error output to automated welding interface, contact SYN_A
SRo	off AC synchronisation or hot wire (factory setting)
, <u> </u>	FSn Error signal, negative logic
	FSP Error signal, positive logic
	AvC AVC (Arc voltage control) connection
AUE	Automation menu
	Fast take-over of control voltage (automation)
FRu	• on = function on
	off = function off (factory setting)
	Orbital welding
orb	• off = off (ex works)
	on = on Orbital welding
0[[]	Correction value for orbital current



Display	Setting/selection		
Seul	Service menu		
	Modifications to the service menu may only be carried out by authorised maintenance staff!		
	Reset (reset to factory settings)		
	off = aus (factory setting)		
	CFG = Reset the values in the machine configuration menu		
	CPL = Complete reset of all values and settings		
The reset is performed when leaving the menu (EXIT).			
	Automated/Manual (rC on/off) operating mode		
	Select machine/function control		
	on: with external control voltages/signals		
	off: with machine control		
	Software version query (example)		
	07= System bus ID		
	0340= Version number		
	System bus ID and version number are separated by a dot.		
	Only qualified service personnel may change the parameters!		
	Ignition pulse limit		
	Setting 0 ms-15 ms (increments of 1 ms)		



6 Maintenance, care and disposal

DANGER

Risk of injury from electric shock!

Cleaning machines that are not disconnected from the mains can lead to serious injuries!

- Disconnect the machine completely from the mains.
- Remove the mains plug!
- Wait for 4 minutes until the capacitors have discharged!

6.1 General

When used in the specified environmental conditions and under normal operating conditions, this machine is largely maintenance-free and requires a minimum of care.

There are some points, which should be observed, to guarantee fault-free operation of your welding machine. Among these are regular cleaning and checking as described below, depending on the pollution level of the environment and the length of time the unit is in use.

6.2 Maintenance work, intervals

6.2.1 Daily maintenance tasks

6.2.1.1 Visual inspection

- Mains supply lead and its strain relief
- Check the wearing parts in the torch.
- Check torch, hose package and power connections for exterior damage and replace or have repaired by specialist staff as necessary!
- Other, general condition

6.2.1.2 Functional test

- · Operating, message, safety and adjustment devices (Functional test)
- · Check correct mounting of the wire spool.
- Blow compressed air free from oil and condensates through the wire feed from the direction of the euro torch connector.
- Welding current cables (check that they are fitted correctly and secured)
- Gas tubes and their switching equipment (solenoid valve)
- · Gas cylinder securing elements

6.2.2 Monthly maintenance tasks

6.2.2.1 Visual inspection

- Casing damage (front, rear and side walls)
 - · Wheels and their securing elements
 - Transport elements (strap, lifting lugs, handle)

6.2.2.2 Functional test

- Selector switches, command devices, emergency stop devices, voltage reducing devices, message and control lamps
- · Check coolant tubes and their connections for impurities
- Check that the wire guide elements (inlet nipple, wire guide tube) are fitted securely.
- Check that all connections and wearing parts are hand-tight and tighten if necessary.
- Check the wire guide.
- Check and clean the welding torch. Deposits in the torch can cause short circuits and have a negative impact on the welding result, ultimately causing damage to the torch.
- Check that all screw and plug connections and replaceable parts are secured correctly, tighten if necessary.



6.2.3 Annual test (inspection and testing during operation)

The welding machine may only be tested by competent, capable personsl. A capable person is one who, because of his training, knowledge and experience, is able to recognise the dangers that can occur while testing welding power sources as well as possible subsequent damage and who is able to implement the required safety procedures.

NOTE

For further information, please see the accompanying supplementary sheets "Machine and Company Data, Maintenance and Testing, Warranty"!

A periodic test according to IEC 60974-4 "Periodic inspection and test" has to be carried out. In addition to the regulations on testing given here, the relevant local laws and regulations must also be observed.

6.3 Maintenance work

🚹 DANGER



Do not carry out any unauthorised repairs or modifications! To avoid injury and equipment damage, the unit must only be repaired or modified by specialist, skilled persons!

The warranty becomes null and void in the event of unauthorised interference.

Appoint only skilled persons for repair work (trained service personnel)!

CAUTION



Electric current! Repairs may only be carried out by authorised specialist staff!

- Do not remove the torch from the hose package!
- Never clamp the torch body in a vice or similar, as this can cause the torch to be irreparably destroyed!
- If damage occurs to the torch or to the hose package which cannot be corrected as part of the maintenance work, the entire torch must be returned to the manufacturer

Repair and maintenance work may only be performed by qualified authorised personnel; otherwise the right to claim under warranty is void. In all service matters, always consult the dealer who supplied the machine. Return deliveries of defective equipment subject to warranty may only be made through your dealer. When replacing parts, use only original spare parts. When ordering spare parts, please quote the machine type, serial number and item number of the machine, as well as the type designation and item number of the spare part.

Disposing of equipment



6.4 Disposing of equipment

NOTE

Proper disposal!

The machine contains valuable raw materials, which should be recycled, and electronic components, which must be disposed of.

- Do not dispose of in household waste!
- Observe the local regulations regarding disposal!

6.4.1 Manufacturer's declaration to the end user

According to European provisions (guideline 2002/96/EG of the European Parliament and the Council
of January, 27th 2003), used electric and electronic equipment may no longer be placed in unsorted
municipal waste. It must be collected separately. The symbol depicting a waste container on wheels
indicates that the equipment must be collected separately.

This machine is to be placed for disposal or recycling in the waste separation systems provided for this purpose.

- According to German law (law governing the distribution, taking back and environmentally correct disposal of electric and electronic equipment (ElektroG) from 16.03.2005), used machines are to be placed in a collection system separate from unsorted municipal waste. The public waste management utilities (communities) have created collection points at which used equipment from private households can be disposed of free of charge.
- Information about giving back used equipment or about collections can be obtained from the respective municipal administration office.
- EWM participates in an approved waste disposal and recycling system and is registered in the Used Electrical Equipment Register (EAR) under number WEEE DE 57686922.
- In addition to this, returns are also possible throughout Europe via EWM sales partners.

6.5 Meeting the requirements of RoHS

We, EWM AG Mündersbach, hereby confirm that all products supplied by us which are affected by the RoHS Directive, meet the requirements of the RoHS (Directive 2002/95/EC).



7 Rectifying faults

All products are subject to rigorous production checks and final checks. If, despite this, something fails to work at any time, please check the product using the following flowchart. If none of the fault rectification procedures described leads to the correct functioning of the product, please inform your authorised dealer.

7.1 Checklist for rectifying faults

NOTE
The correct machine equipment for the material and process gas in use is a fundamental requirement for perfect operation!

Legend	Symbol	Description
	N	Fault/Cause
	*	Remedy

Coolant error/no coolant flowing

✓ Insufficient coolant flow

- ℜ Check coolant level and refill if necessary
- ★ Eliminate kinks in conduit system (hose packages)
- \boldsymbol{x} Reset automatic cutout of the coolant pump by activating
- ✓ Air in the coolant circuit
 - see chapter "Vent coolant circuit"

Functional errors

- ✗ Insufficient coolant flow
 - ℜ Check coolant level and refill if necessary
 - ✤ Eliminate kinks in conduit system (hose packages)
 - ***** Reset automatic cutout of the coolant pump by activating
- ✓ Air in the coolant circuit
 - ℜ see chapter "Vent coolant circuit"
- ✓ Machine control without displaying the signal lights after switching on
 - ℜ Phase failure > check mains connection (fuses)
- ✓ No welding performance
 - ✤ Phase failure > check mains connection (fuses)
- ✓ Various parameters cannot be set
 - Entry level is blocked, disable access lock (see chapter entitled "Lock welding parameters against unauthorised access")
- ✗ Connection problems
 - x Make control lead connections and check that they are fitted correctly.

Welding torch overheated

- ✗ Loose welding current connections
 - ***** Tighten power connections on the torch and/or on the workpiece
 - ★ Tighten contact tip correctly
- ✓ Overload
 - ☆ Check and correct welding current setting
 - \boldsymbol{x} Use a more powerful welding torch

Rectifying faults

Checklist for rectifying faults



Wire feed problems

- ✗ Unsuitable or worn welding torch equipment
 - * Adjust contact tip (cold wire/hot wire) to wire diameter, blow through and replace if necessary
 - Adjust wire guide to material in use, blow through and replace if necessary
- Contact tip blocked
 - lpha Clean, spray with anti-spatter spray and replace if necessary
 - Y Setting the spool brake (see "Setting the spool brake" chapter)
 - ★ Check settings and correct if necessary
- ✓ Setting pressure units (see "Inching wire electrodes" chapter)
 - ☆ Check settings and correct if necessary
- ✓ Worn wire rolls
 - ℜ Check and replace if necessary
- ✓ Wire feed motor without supply voltage (automatic cutout triggered by overloading)
 - \boldsymbol{x} Reset triggered fuse (rear of the power source) by pressing the key button
- ✗ Kinked hose packages
 - Extend and lay out the torch hose package
- ✗ Incompatible parameter settings
 - ℜ Check settings and correct if necessary
- ✓ Arc between gas nozzle and workpiece (metal vapour on the gas nozzle)
 - 🛠 🛛 Replace gas nozzle

No arc ignition

- ✗ Incorrect ignition type setting.
 - ★ Set ignition type changeover switch to the HF ignition setting.

Bad arc ignition

- Material inclusions in the tungsten electrode due to contact with filler material or workpiece
 Regrind or replace the tungsten electrode
- ✗ Bad current transfer on ignition
 - ☆ Check the setting on the "Tungsten electrode diameter/Ignition optimisation" rotary dial and increase if necessary (higher ignition energy).

Unstable arc

- ✓ Material inclusions in the tungsten electrode due to contact with filler material or workpiece
 - ***** Regrind or replace the tungsten electrode
- ✗ Incompatible parameter settings
 - ℜ Check settings and correct if necessary

Pore formation

- ✗ Inadequate or missing gas shielding
 - lpha Check shielding gas setting and replace shielding gas cylinder if necessary
 - Shield welding site with protective screens (draughts affect the welding result)
 - ✤ Use gas lens for aluminium applications and high-alloy steels
- Unsuitable or worn welding torch equipment
 - ★ Check size of gas nozzle and replace if necessary
- ✓ Condensation (hydrogen) in the gas tube
 - ℜ Purge hose package with gas or replace



7.2 Machine faults (error messages)

NOTE

A welding machine error is indicated by the collective fault signal lamp (A1) lighting up and an error code (see table) being displayed in the machine control display. In the event of a machine error, the power unit shuts down.

- If multiple errors occur, these are displayed in succession.
- Document machine errors and inform service staff as necessary.

Error message	Possible cause	Remedy
Err 3	Speedometer error	Check wire guide/hose package
	Wire feeder is not connected	 Switch off cold wire mode in the device configuration menu (off status) Connect the wire feeder
Err 4	Temperature error	Allow the machine to cool down
	Error in emergency stop circuit (interface for automated welding)	Check the external interrupt equipmentCheck jumper JP 1 on PCB T320/1
Err 5	Overvoltage	Switch off machine and check the mains
Err 6	Low voltage	voltage
Err 7	Coolant error (with connected cooling unit only)	Check coolant level and refill if necessary
Err 8	Gas error	Check gas supply
Err 9	Secondary overvoltage	Switch machine off and on again,
Err 10	PE error	inform the service department if the error continues
Err 11	FastStop position	Edge 'Acknowledge error' signal (0 to 1) via robot interface (if available)
Err 12	VRD error	Switch the machine off and on again. If the error persists, inform the service dept.
Err 16	Pilot arc current	Check welding torch
Err 17	Cold wire error Excess current limit of a motor control card has been triggered Cold wire error – a permanent deviation between wire nominal value and actual value or a blocked drive has been detected in the process	 Inspect the wire feed system (drives, tube packages, torch): Check cold wire on the torch / work piece (moved against work piece?) Check relation of process wire feed speed to robot travel speed, and correct if necessary Check wire feed for stiffness with wire inching function (resolve by checking wire guides section by section) Reset error via robot interface (reset error)
Err 18	Plasma gas error Nominal value significantly different from actual value -> No plasma gas?	 Check plasma gas supply; use the plasma gas test function on "cold wire feed unit" if necessary
Err 19	Shielding gas Nominal value significantly different from actual value -> No shielding gas?	 Check guiding / connections of the gas supply hose for leaks / kinks Check that the gas supply lead of the plasma torch is not blocked Reset error via robot interface (reset error)

The display of possible error numbers depends on the machine version (interfaces/functions).

Rectifying faults

Machine faults (error messages)



Error message	Possible cause	Remedy	
Err 20	Coolant The flow quantity of the torch coolant has fallen below the permissible minimum -> the coolant flow is dirty or cut off because the tube package has been unsuitably installed The flow quantity of the torch coolant has fallen below the permissible level	 Check coolant level and refill if necessary Check coolant level in the reverse cooler Check coolant lines for leaks and kinks Check that the coolant inlet and outlet on the plasma torch is not blocked Reset error via robot interface (reset error) 	
Err 22	Excess temperature in coolant circuit Coolant temperature exceeded The temperature of the coolant is too high	 Check coolant level in the reverse cooler Check temperature nominal value on the cooling unit Reset error via robot interface (reset error) 	
Err 23	HF choke excess temperature High frequency blocking inductor excess temperature The excess temperature of the high frequency blocking inductor has triggered	 Allow equipment to cool down Adjust processing cycle times if necessary Reset error via robot interface (reset error) 	
Err 32	Electronics error (I>0 error)		
Err 33	Electronics error (Uactual error)	- Switch the mechine off and an again	
Err 34	Electronics error (A/D channel error)	Switch the machine off and on again. If the error persists, inform the service dept.	
Err 35	Electronics error (edge error)		
Err 36	Electronics error (S sign)		
Err 37	Electronics error (temperature error)	Allow machine to cool down.	
Err 38		Switch the mechine off and an again	
Err 39	Electronics error (secondary overvoltage)	Switch the machine off and on again. If the error persists, inform the service dept.	
Err 48	Ignition error	Check welding process	
Err 49	Arc interruption	Inform the Service department	
Err 51	Error in emergency stop circuit (interface for automated welding)	Check the external interrupt equipmentCheck jumper JP 1 on PCB T320/1	

NOTE

If the industrial bus interface is connected error messages are output via the respective interface. It may occur that error messages output from the power source and the interface differ.



Please note the relevant documentation of the accessory components.



7.3 Resetting welding parameters to the factory settings

All customised welding parameters that are stored will be replaced by the factory settings.

NOTE

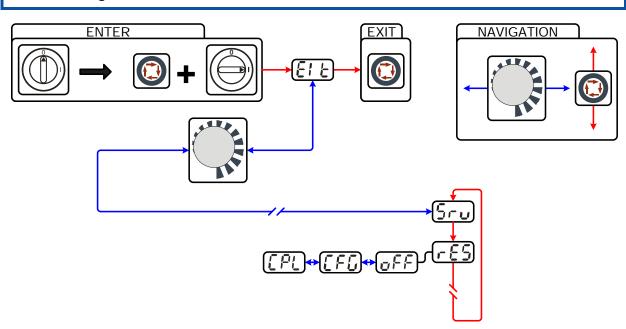


Figure 7-1

Display	Setting/selection
	Exit the menu
	Exit
	Service menu
	Modifications to the service menu may only be carried out by authorised maintenance staff!
	Reset (reset to factory settings)
	off = aus (factory setting)
	CFG = Reset the values in the machine configuration menu
	CPL = Complete reset of all values and settings
	The reset is performed when leaving the menu (EXIT).
	Switch off
	Switching off machine function
	Reset machine configuration
	Resetting the values in the machine configuration menu
	Complete reset
	Complete reset of all values and settings by the factory settings

Rectifying faults

Display machine control software version



7.4 Display machine control software version

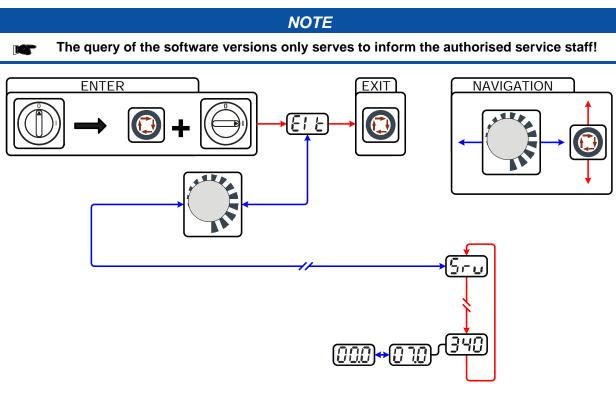


Figure 7-2

Display	Setting/selection
	Exit the menu
	Exit
	Service menu
<u>טרט</u>	Modifications to the service menu may only be carried out by authorised maintenance staff!
	Software version query (example)
	07= System bus ID
	0340= Version number
	System bus ID and version number are separated by a dot.

7.5 General operating problems

7.5.1 Interface for automated welding



No function of the external interrupt equipment (emergency stop switch)! If the emergency stop circuit has been realised using an external interrupt equipment via the interface for automated welding, the machine must be configured for this setup. If this is not observed, the power source will ignore the external interrupt equipment and will not shut down!

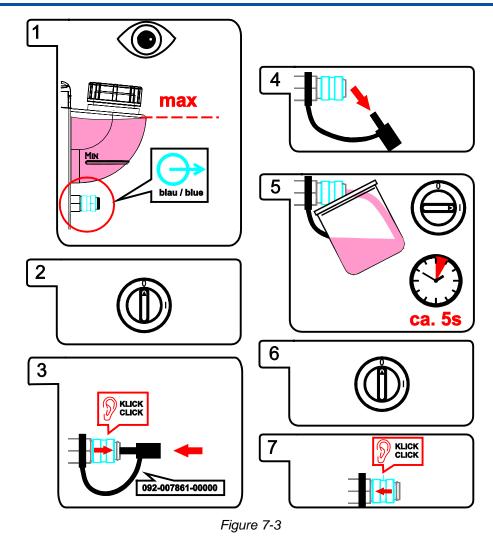
• Disconnect jumper 1 on PCB T320/1 (Tetrix) or M320/1 (Phoenix / alpha Q)!



7.6 Vent coolant circuit



- Coolant tank and quick connect coupling of coolant supply and return are only fitted in machines with water cooling.
- To vent the cooling system always use the blue coolant connection, which is located as deep as possible inside the system (close to the coolant tank)!





8 Technical data

NOTE

Performance specifications and guarantee only in connection with original spare and replacement parts!

8.1 Tetrix 352 AC/DC SYNERGIC PL. AW GR

	352
Welding current	5 A to 350
Welding voltage	25.2 V to 39.0 V
Plasma current (Pilot arc)	5 A to 80 A (factory setting 10 A, can be adjusted using PCT 300 software)
Duty cycle at 40 °C ambient temperature	
100% DC	350 A
60% DC	300 A
Load alternation	10 min. (60% DC $ riangle$ 6 min. welding, 4 min. pause)
Floating voltage	100 V
Mains voltage (tolerances)	3 x 400 V (-25% to +20%)
Frequency	50/60 Hz
Mains fuse (safety fuse, slow-blow)	3 x 25 A
Mains connection lead	H07RN-F5G6
Max. connected load	18.6 kVA
Recommended generator rating	25.1 kVA
Cosφ	0.99
Insulation class/protection classification	F/IP 23
Ambient temperature*	-10 °C to +40 °C*
Machine cooling/torch cooling	Fan/gas or water
Workpiece lead	70 mm ²
Dimensions L x W x H in mm	
Weight	160 kg
EMC class	A
Constructed to standards	IEC 60974-1, -3, -10; [S]; С Є
	NOTE

* Ambient temperature depends on coolant!

Observe the coolant temperature range for the welding torch cooling!



9 Accessories

NOTE

Performance-dependent accessories like torches, workpiece leads, electrode holders or intermediate hose packages are available from your authorised dealer.

9.1 Welding torch cooling system

Туре	Designation	Item no.
cool82 U44	Cooling module for robot welding machines	090-008268-00502
cool82 U45	Cooling module for robot welding machines	090-008280-00502
RK1	Reverse cooling unit	094-002283-00000
RK2	Reverse cooling unit	094-002284-00000
RK3	Reverse cooling unit	094-002285-00000
UKV4SET 4M	Hose connection set	092-000587-00000
KF 23E-10	Coolant (-10 °C), 9.3 I	094-000530-00000
KF 23E-200	Coolant (-10 °C), 200 litres	094-000530-00001

9.2 Wire feed units

Туре	Designation	Item no.		
T drive 4 Rob 3 RE Hotwire	Wire feeder for automated applications, hot wire, gas-cooled, opens on right with integrated IG3 speedometer solution	090-008702-00502		
T drive 4 Rob 3 LI Hotwire	Wire feeder for automated applications, hot wire, gas-cooled, opens on left with integrated IG3 speedometer solution	090-008703-00502		

9.3 General accessories

Туре	Designation	Item no.
DM/ARGON	"Constant" pressure regulator	096-000000-00000
DM/H2	"Constant" pressure regulator	096-000001-00000
GH 2X1/4" 2M	Gas hose	094-000010-00001
2M-G1/4"+G3/8"/DIN EN 559	Gas tube, 2 m	092-000525-00001

9.4 Connection cables, connection sockets

Туре	Designation	ltem no.
5POLE/CEE/32A/M	Machine plug	094-000207-00000

9.5 Options

Туре	Designation	Item no.		
ON Key Switch	Optional retrofit kit for key switch	092-001828-00000		
ON SENSOR UNIT WIRE END	Wire end sensor	092-001190-00000		

9.6 Computer communication

Туре	Designation	ltem no.
RC 300	EWM tablet PC incl. software, adapter and interface	090-008238-00002
PC300.Net	PC300.Net welding parameter software kit incl. cable and SECINT X10 USB interface	090-008777-00000
QDOC9000 V2.0	Set consisting of interface, documentation software, connection lead	090-008713-00000
CD PC300.Net update	PC300.Net Update on CD-ROM	092-008172-00001

Interfaces



9.7 Interfaces

Туре	Designation	ltem no.						
Tetrix BUSINT X11 PLASMA RUGGED LINE	RUGGED LINE industrial bus interface in casing	090-008623-00000						
Tetrix BUSINT X11 PLASMA PROFIBUS ATCASE	PROFIBUS industrial bus interface in casing	090-008624-00000						
Tetrix BUSINT X11 PLASMA PROFINET LWL ATCASE	PROFINET LWL industrial bus interface in casing	090-008625-00000						
Tetrix BUSINT X11 PLASMA CAN-OPEN ATCASE	CAN-OPEN industrial bus interface in casing	090-008689-00000						
Tetrix BUSINT X11 PLASMA DEVICE NET ATCASE	DEVICE NET industrial bus interface in casing	090-008690-00000						
Connection and extension cables								
Туре	Designation	Item no.						

9.8

Туре	Designation	Item no.
FRV 7POL 5 m	Extension/connecting cable	092-000201-00003
FRV 7POL 10 m	Extension/connecting cable	092-000201-00000
FRV 7POL 20 m	Extension/connecting cable	092-000201-00001
RA5 19POL 5M	Remote control e.g. connection cable	092-001470-00005
RA10 19POL 10M	Remote control e.g. connection cable	092-001470-00010



10 Circuit diagrams

NOTE

Original format circuit diagrams are located inside the machine.

10.1 Tetrix 352 AC/DC SYNERGIC PL. AW GR

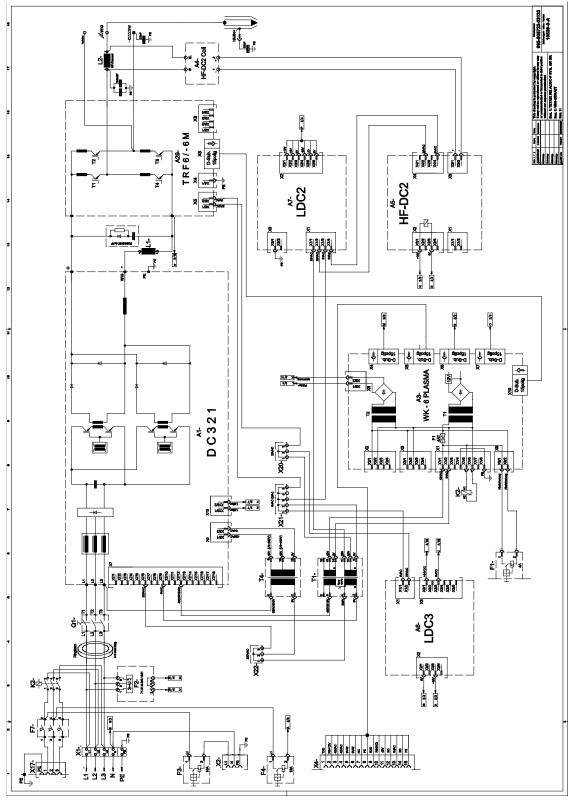


Figure 10-1



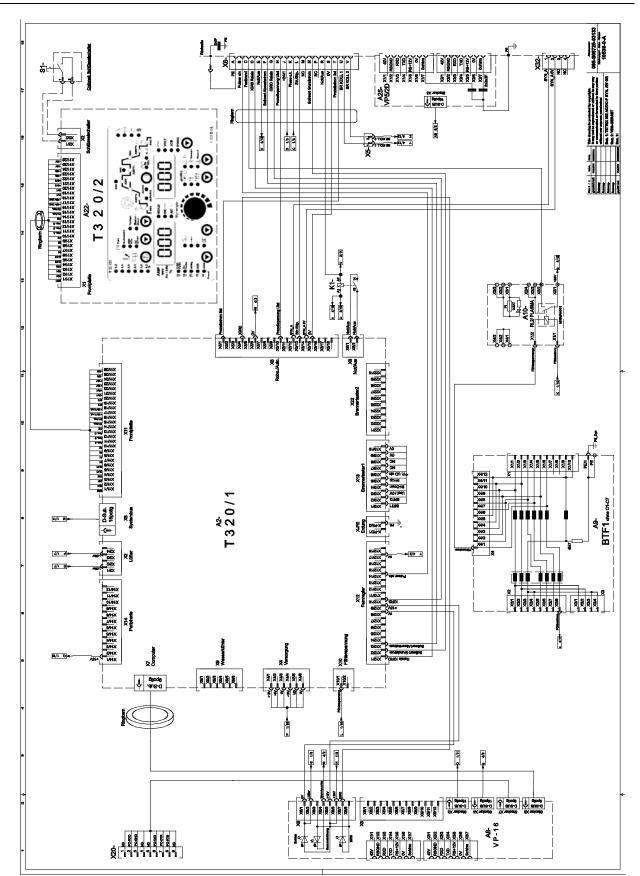


Figure 10-2



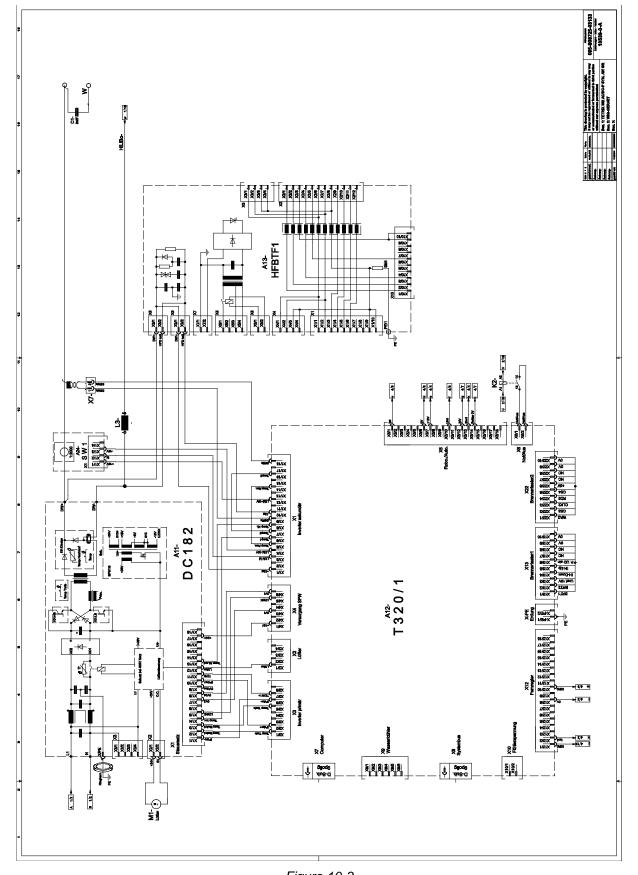


Figure 10-3

ew



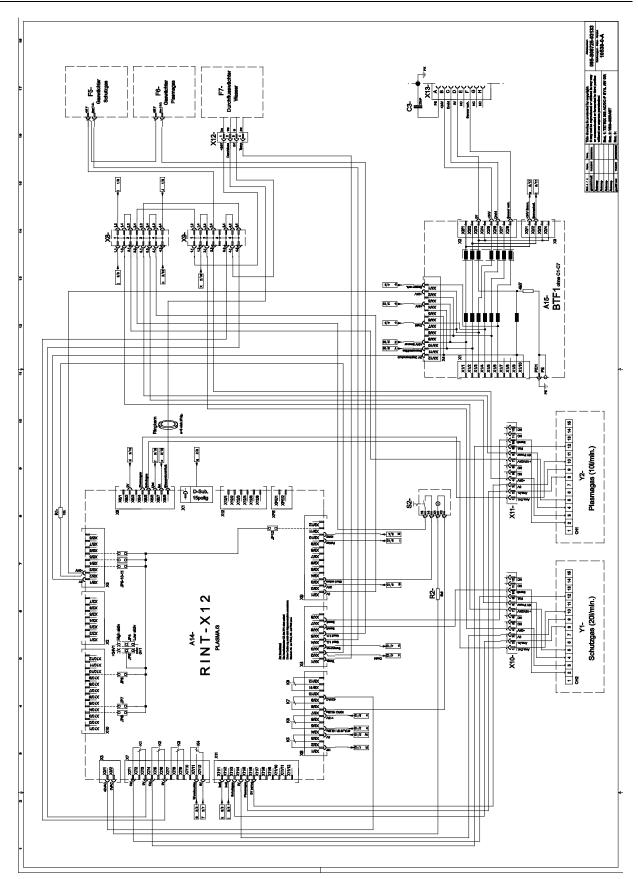


Figure 10-4

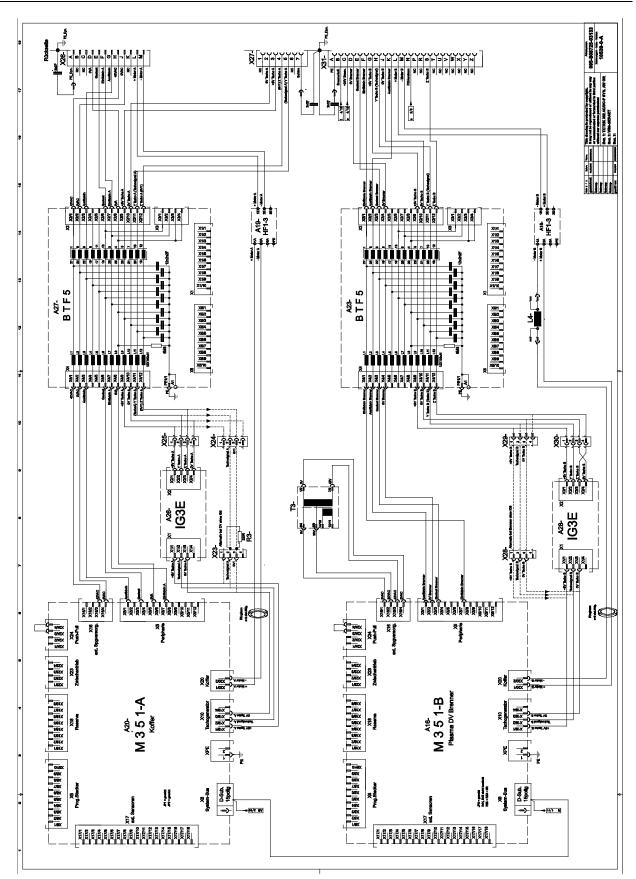


Figure 10-5

ew



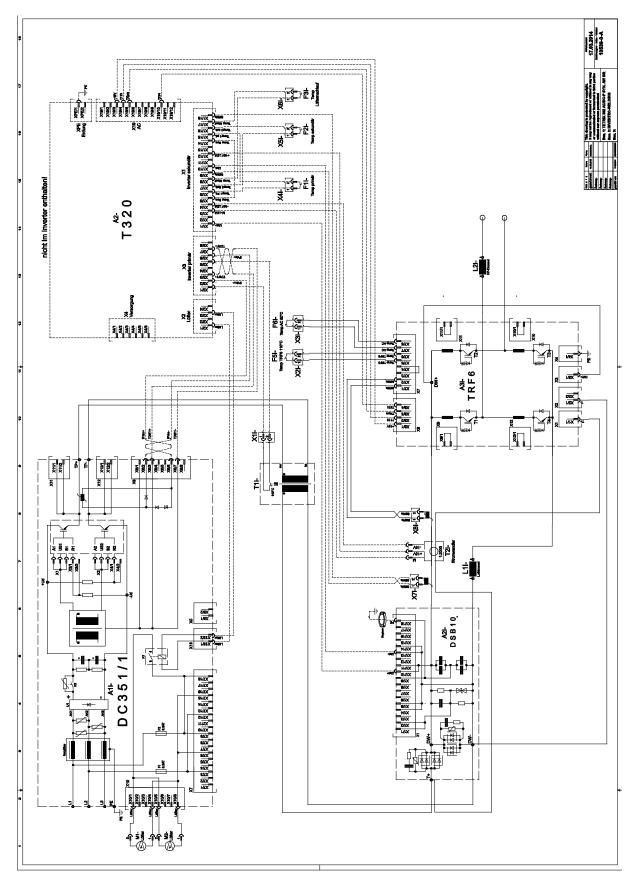


Figure 10-6



11 Appendix A

11.1 JOB-List

L	F	Proc	ces	s	Material		V	Vire	e		S	eam	positi	on	
		TIG hot wire	TIG cold wire					Ø			Fillet weld	Butt joint	Fillet weld lap joint	Vertical-down weld	Tungsten electrode Ø
JOB	ЦG	TIG	TIG	MMA		0,6	0,8	1,0	1,2	1,6	Ŀ				ø → +
1	Re	serv	ved												
2	Ø				CrNi/ Fe/ St						\checkmark				1
3	☑				CrNi/ Fe/ St						$\mathbf{\nabla}$				1.6
	Ø				CrNi/ Fe/ St						$\mathbf{\nabla}$				2
5	\checkmark		$\mathbf{\nabla}$		CrNi/ Fe/ St		\checkmark	\checkmark	\checkmark		V				2.4
	Ø		\checkmark		CrNi/ Fe/ St		\checkmark	\checkmark	\checkmark		\checkmark				3.2
	\checkmark		$\mathbf{\nabla}$		CrNi/ Fe/ St		\checkmark	\checkmark	\checkmark		V				>3.2
	Ø				CrNi/ Fe/ St							\checkmark			1
9	Ø				CrNi/ Fe/ St							\checkmark			1.6
10	Ø				CrNi/ Fe/ St							$\mathbf{\nabla}$			2
11	Ø		$\mathbf{\nabla}$		CrNi/ Fe/ St		$\mathbf{\nabla}$	V	V			\checkmark			2.4
12	Ø		$\mathbf{\nabla}$		CrNi/ Fe/ St		$\mathbf{\nabla}$	V	V			\checkmark			3.2
13	\checkmark		$\mathbf{\nabla}$		CrNi/ Fe/ St		\checkmark	\checkmark	\checkmark			\square			>3.2
14	Ø				CrNi/ Fe/ St								\checkmark		1
15	V				CrNi/ Fe/ St								V		1.6
16	Ø				CrNi/ Fe/ St								\checkmark		2
17	☑		\checkmark		CrNi/ Fe/ St		V	\checkmark	\checkmark				\checkmark		2.4
18	☑		\blacksquare		CrNi/ Fe/ St		\blacksquare	\checkmark	Ø				\checkmark		3.2
19	☑		\blacksquare		CrNi/ Fe/ St		\blacksquare	Ø	\blacksquare				$\overline{\mathbf{V}}$		>3.2
20	☑				CrNi/ Fe/ St									V	1
21	\checkmark				CrNi/ Fe/ St									V	1.6
22	N				CrNi/ Fe/ St									V	2
23	V		Ø		CrNi/ Fe/ St		Ø	A	J					V	2.4
24	V		$\mathbf{\nabla}$		CrNi/ Fe/ St		\checkmark	\checkmark	A					V	3.2
25	V		$\mathbf{\nabla}$		CrNi/ Fe/ St		V	\checkmark	A					V	>3.2
26	V				Cu/CuZn						Ā				1
27	V				Cu/CuZn						Ā				1.6
28	V				Cu/CuZn						V				2
29	☑		$\mathbf{\nabla}$		Cu/CuZn			\checkmark			V				2.4
30	☑		$\mathbf{\nabla}$		Cu/CuZn			\checkmark			V				3.2
31	V				Cu/CuZn						V				>3.2
32	☑				Cu/CuZn							V			1
33	V				Cu/CuZn							V			1.6
34	V				Cu/CuZn							V			2
35	Ø		V		Cu/CuZn			Ø				V			2.4

Appendix A JOB-List



	I	Pro	ces	s	Material		N	Nire	e		S	1			
		TIG hot wire	TIG cold wire					Ø			Fillet weld	Butt joint	Fillet weld lap joint	Vertical-down weld	Tungsten electrode \varnothing
JOB	TIG	TIG I	TIG (MMA		0,6	0,8	1,0	1,2	1,6	B	-			ø → +
36	\checkmark		Þ		Cu/CuZn			\checkmark				N			3.2
37	$\mathbf{\nabla}$				Cu/CuZn							$\mathbf{\Sigma}$			>3.2
38	\checkmark				Cu/CuZn								$\overline{\mathbf{V}}$		1
39	\checkmark				Cu/CuZn								\checkmark		1.6
40	Ø				Cu/CuZn								V		2
41	\checkmark		V		Cu/CuZn			Ø					V		2.4
42	\checkmark		\checkmark		Cu/CuZn			V					V		3.2
43	\checkmark				Cu/CuZn								\checkmark		>3.2
44	\checkmark				Cu/CuZn									Ø	1
45	V				Cu/CuZn									V	1.6
46	V				Cu/CuZn									Ø	2
47	V		V		Cu/CuZn			V						Ø	2.4
48	V		V		Cu/CuZn			V						Ø	3.2
49	V				Cu/CuZn									Ø	>3.2
50	\square				AIMg						\checkmark				1
51	V				AlMg						\checkmark				1.6
52	V				AlMg						\checkmark				2
53	V		V		AlMg				V	V	\checkmark				2.4
54	V		V		AlMg				V	V	\checkmark				3.2
55	\checkmark		$\mathbf{\nabla}$		AlMg				V	V	\checkmark				>3.2
56	$\mathbf{\nabla}$				AlMg							\checkmark			1
57	V				AIMg							\checkmark			1.6
58	V				AIMg							\checkmark			2
59	V		V		AlMg				V	V		V			2.4
60	V		V		AlMg				V	V		V			3.2
61	\square		$\mathbf{\nabla}$		AlMg				V	V		$\mathbf{\nabla}$			>3.2
62	V				AlMg								\checkmark		1
63	V				AlMg								\checkmark		1.6
64	Ø				AlMg								\checkmark		2
65	V		$\mathbf{\nabla}$		AlMg				V	V			\checkmark		2.4
66	V		Ŋ		AlMg				V	V			\checkmark		3.2
67	V		V		AlMg				V	V			V		>3.2
68					AlMg										1
69	V				AlMg										1.6
70					AlMg									Ø	2
71			V		AlMg				$\mathbf{\nabla}$	Ø				Ø	2.4
72			V		AlMg				$\mathbf{\nabla}$	V				Ø	3.2
73	Ø		V	l	AlMg				V	Ø				Ø	>3.2



	F	Pro	ces	S	Material		N	Nire	e		S				
		TIG hot wire	TIG cold wire					Ø			Fillet weld Butt joint Fillet weld lap joint Vertical-down weld			Vertical-down weld	Tungsten electrode Ø
JOB	TIG	TIG	TIG	MMA		0,6	0,8	1,0	1,2	1,6		-			ø → ←
74	\mathbf{V}				AlSi						V				1
75	\checkmark				AlSi						\checkmark				1.6
76	$\mathbf{\nabla}$				AlSi						V				2
77	\checkmark		\checkmark		AlSi				V		$\mathbf{\nabla}$				2.4
78	\checkmark		\checkmark		AlSi				\checkmark		\mathbf{N}				3.2
79	$\mathbf{\nabla}$		$\mathbf{\nabla}$		AlSi				V		\checkmark				>3.2
80	$\mathbf{\nabla}$				AlSi							\checkmark			1
81	☑				AlSi							\checkmark			1.6
82	V				AlSi							\square			2
83	V		V		AlSi				V			V			2.4
84	V		\mathbf{V}		AlSi				\mathbf{V}			\checkmark			3.2
85	V		V		AlSi				\mathbf{N}			\checkmark			>3.2
86	V				AlSi								$\mathbf{\nabla}$		1
87	$\mathbf{\nabla}$				AlSi								V		1.6
88	V				AlSi								$\mathbf{\nabla}$		2
89	V		V		AlSi				V				Ø		2.4
90	$\mathbf{\nabla}$		$\mathbf{\nabla}$		AlSi				V				V		3.2
91	V		V		AlSi				V				Ø		>3.2
92	V				AlSi									Ŋ	1
93	V				AlSi									Ŋ	1.6
94	$\mathbf{\nabla}$				AlSi									V	2
95	$\mathbf{\nabla}$		$\mathbf{\nabla}$		AlSi				\checkmark					V	2.4
96	$\mathbf{\nabla}$		$\mathbf{\Lambda}$		AlSi				\checkmark					V	3.2
97	\checkmark		$\mathbf{\nabla}$		AlSi				\mathbf{V}					Ŋ	>3.2
98	☑				Al99						$\mathbf{\nabla}$				1
99	V				Al99						\checkmark				1.6
100	V				Al99						\checkmark				2
101	V		V		Al99				V		\mathbf{V}				2.4
102	V		V		Al99				V		\mathbf{V}				3.2
103	☑		$\mathbf{\nabla}$		Al99				V		$\mathbf{\nabla}$				>3.2
104	V				Al99							\checkmark			1
105	V				Al99							\checkmark			1.6
106	Ø				Al99							V			2
107	V		V		Al99				V			\checkmark			2.4
108	V		V		Al99				Ø			Ø			3.2
109	V		V		Al99				Ø			Ø			>3.2
110	V				Al99								Ø		1
111	V				Al99								V		1.6

Appendix A JOB-List



		Pro	ces	S	Material	Wire						Seam position					
		TIG hot wire	TIG cold wire					Ø			Fillet weld	Butt joint	Fillet weld lap joint	Vertical-down weld	Tungsten electrode Ø		
JOB	TIG	TIG	TIG 0	MMA		0,6	0,8	1,0	1,2	1,6			Н		ø + † ←		
112	$\mathbf{\nabla}$				Al99								N		2		
113	$\mathbf{\nabla}$		V		Al99				V				V		2.4		
114	V		$\mathbf{\nabla}$		Al99				$\mathbf{\nabla}$				$\mathbf{\Sigma}$		3.2		
115	$\mathbf{\nabla}$		$\mathbf{\nabla}$		Al99				$\mathbf{\nabla}$				Ì		>3.2		
116	$\mathbf{\nabla}$				Al99									V	1		
117	$\mathbf{\nabla}$				Al99									V	1.6		
118	$\mathbf{\nabla}$				Al99									V	2		
119	\checkmark		\checkmark		Al99				\checkmark					Ø	2.4		
120	\checkmark		\checkmark		Al99				\checkmark					Ø	3.2		
121	\checkmark		\checkmark		Al99				\checkmark					Ø	>3.2		
122	TIG manual/TIG classic																
123	Classic electrode																
124	Re	ser	ved														
125	Re	ser	ved														
126	Re	ser	ved														
127	Ele	ectro	ode	JOI	3												
128	Re	ser	ved														
129-179	Fre	e J	OB	s or	SCO (e.g. pla	asm	a)										
180	V	\checkmark			CrNi/FeSt		V	\checkmark	\checkmark		\checkmark				2.4		
181	V	V			CrNi/FeSt		V	$\mathbf{\nabla}$	V		\checkmark				3.2		
182	V	V			CrNi/FeSt		V	$\mathbf{\nabla}$	V		\checkmark				>3.2		
183	V	V			CuSi			$\mathbf{\nabla}$			\checkmark				2.4		
184	V	V			CuSi			$\mathbf{\nabla}$			\checkmark				3.2		
185-207		e J 0 or		s or	special custo	me	ror	der	(S0	CO))/TIG	Con	nfort (v	with Sr	mart		
208-215		Free JOBs or special customer order (SCO)/electrode Comfort (with Smart 208 only)															
216-254	Free JOBs or special customer order (SCO)																
255	DC)- w	ith [DC+	- ignition					,							
256	Те	st jo	b: {	5 A ·	to Imax												

□ not possible

☑ possible



12 Appendix B

12.1 Overview of EWM branches

Headquarters

EWM AG Dr. Günter-Henle-Straße 8 56271 Mündersbach · Germany Tel: +49 2680 181-0 · Fax: -244 www.ewm-group.com · info@ewm-group.com

Production, Sales and Service

EWM AG Dr. Günter-Henle-Straße 8 56271 Mündersbach · Germany Tel: +49 2680 181-0 · Fax: -244 www.ewm-group.com · Info@ewm-group.com

EWM HIGHTEC WELDING (Kunshan) Ltd. 10 Yuanshan Road, Kunshan · New & High-tech Industry Development Zone Kunshan · Jiangsu · 215300 · People's Republic of China Tel: +86 512 57867-188 · Fax: -182 www.ewm-kunshan.cn · info@ewm-kunshan.cn

△ Sales and Service Germany

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EWM Schweißtechnik Handels GmbH Heinkelstraße 8 89231 Neu-Ulm · Tel: +49 731 7047939-0 · Fax: -15 www.ewm-neu-ulm.de · info@ewm-neu-ulm.de

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🛆 Branches

More than 300 EWM sales partners worldwide